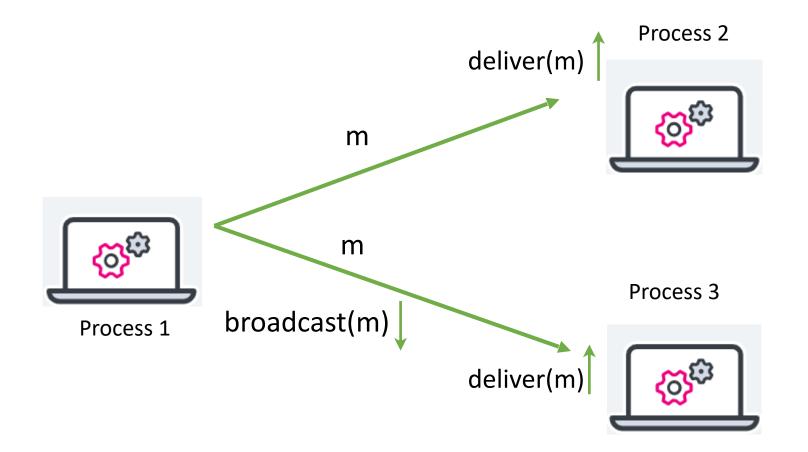
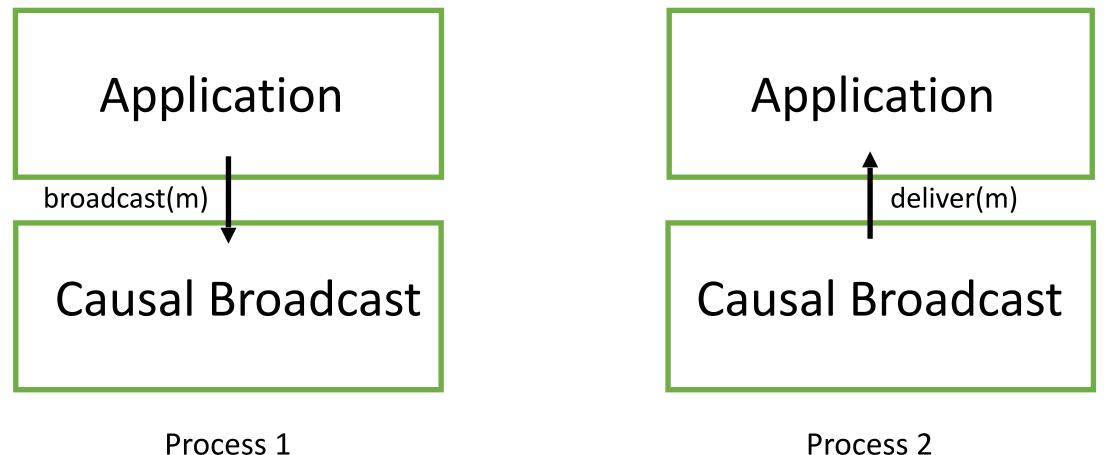
Causal Broadcast

Mohsen Lesani

Broadcast Abstraction

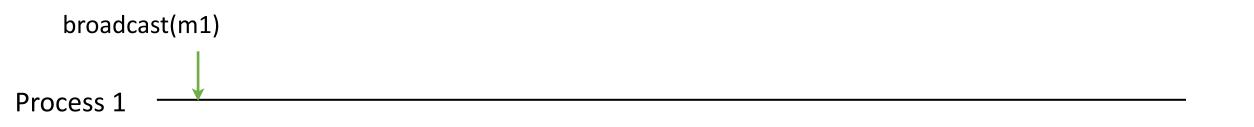


Modular Design



Process 2

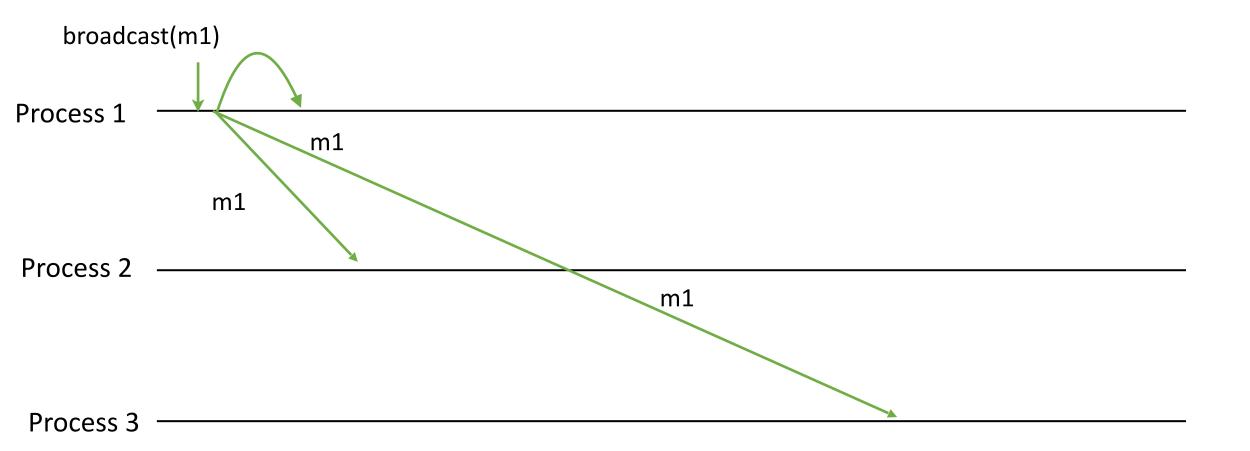
Broadcast Execution Diagram

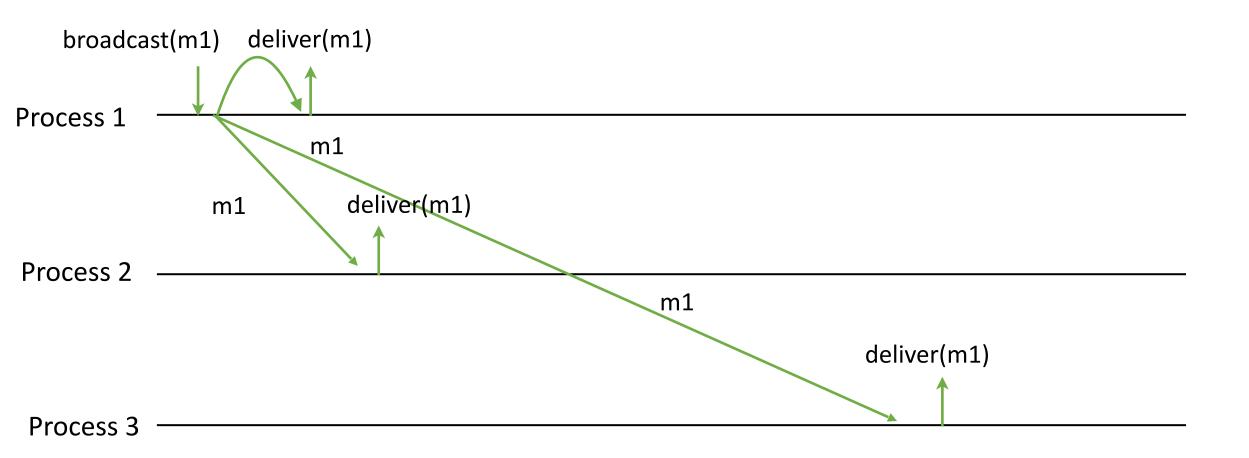


Process 2

Process 3

Broadcast Execution Diagram





Overview

Motivation: why causal broadcast?

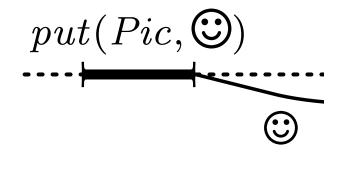
- Properties of causal broadcast
- Protocols

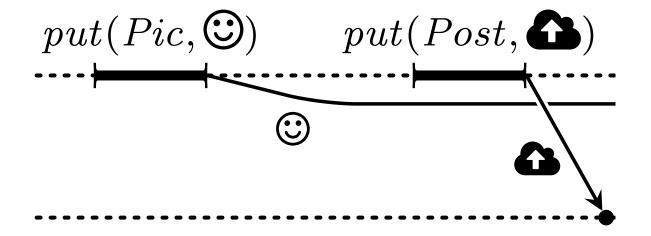
- So far, we did not consider ordering among messages; In particular, we considered messages to be independent
- Two messages from the same process might not be delivered in the order they were broadcast
- A message m1 that causes a message m2 might be delivered by some process after m2
- Consider a news or social network where every new event contains a reference to the event that caused it.

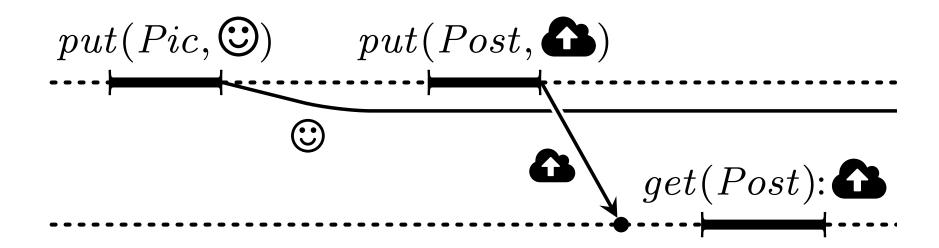
Hey, check out my cool picture.

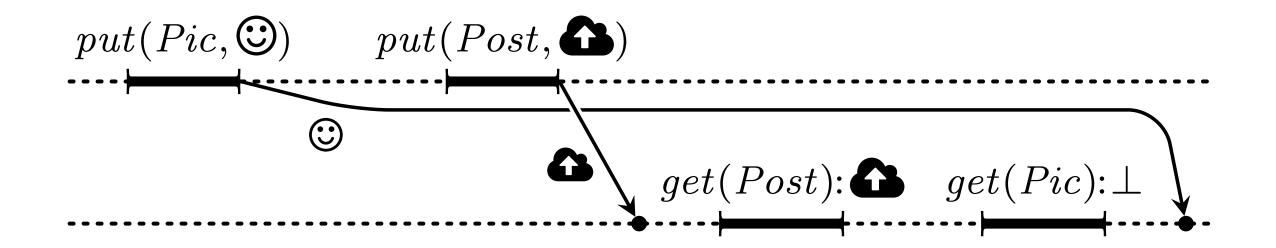
Hey, check out my cool picture.



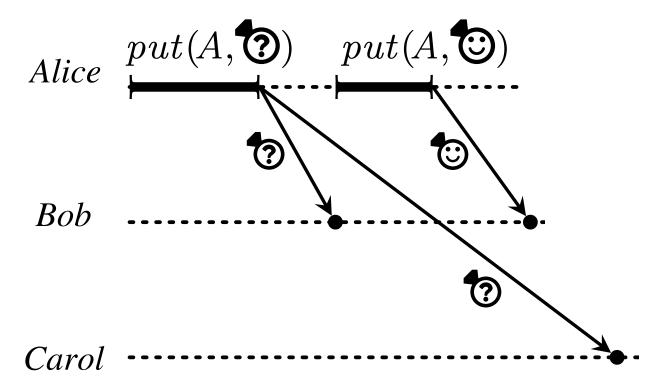




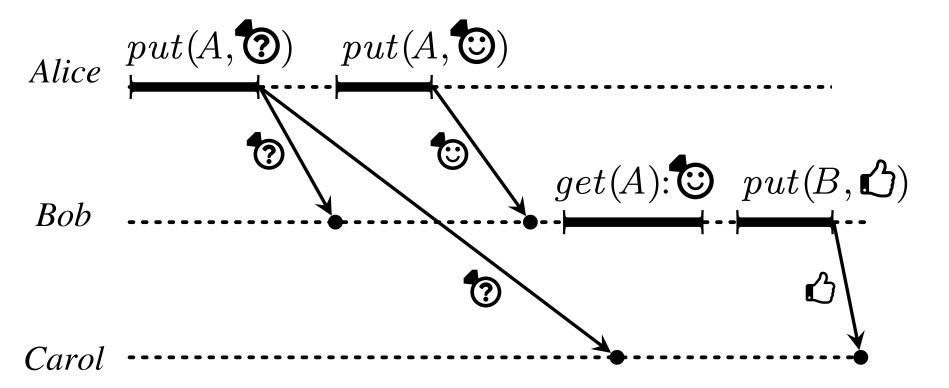




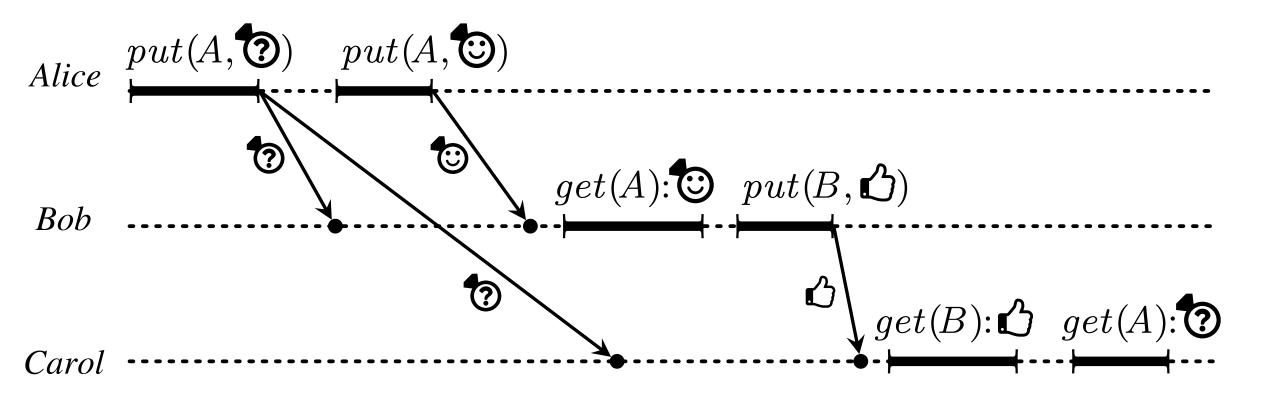
Lost Ring



Lost Ring



Lost Ring



Overview

- Motivation: why causal broadcast?
- Properties of causal broadcast
- Protocols

Causal Order Property

If any process pi delivers a message m2, then pi must have delivered every message m1 that m2 is **dependent** on.

Let m1 and m2 be any two messages. m1 < m2 (m1 is causally before m2, or m2 depends on m1) iff

• FIFO order:

A process pi broadcasts m1 before broadcasting m2.



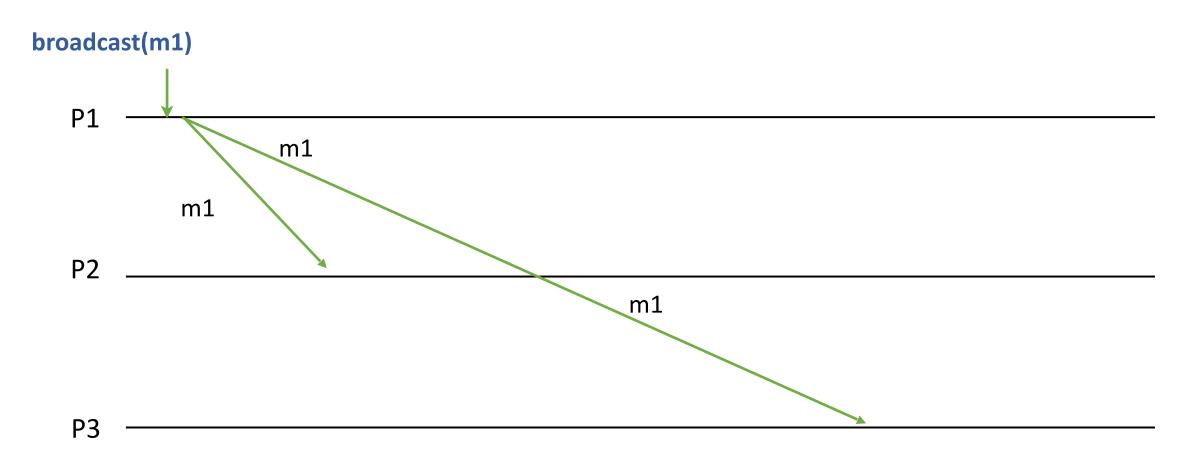
If a process pi broadcasts m1 before broadcasting m2 then m1 < m2.

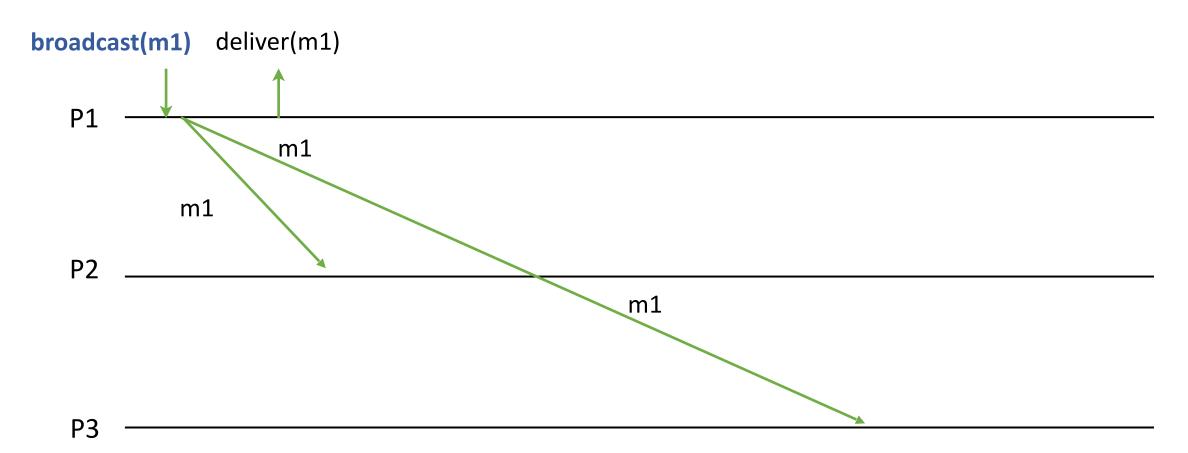
P1 ______ P2 _____

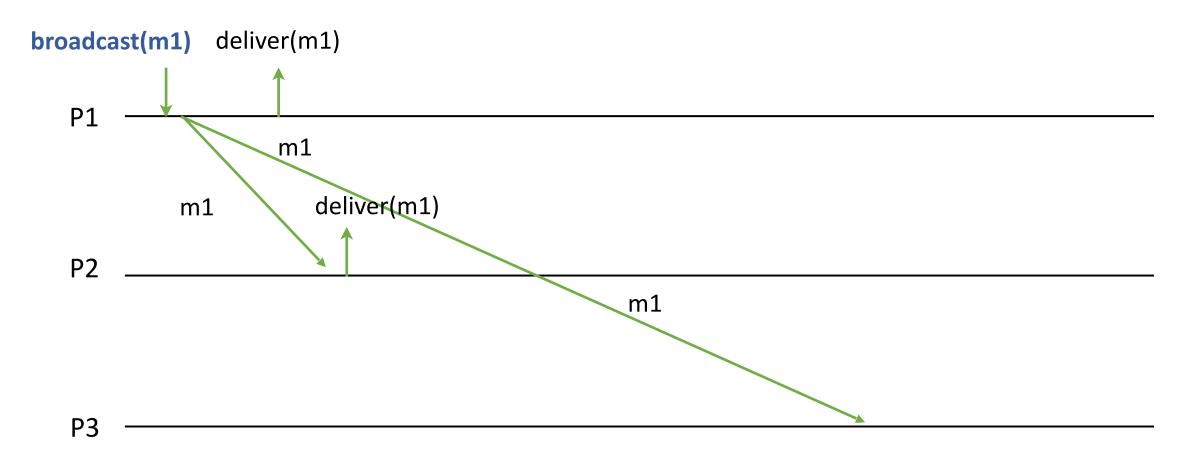


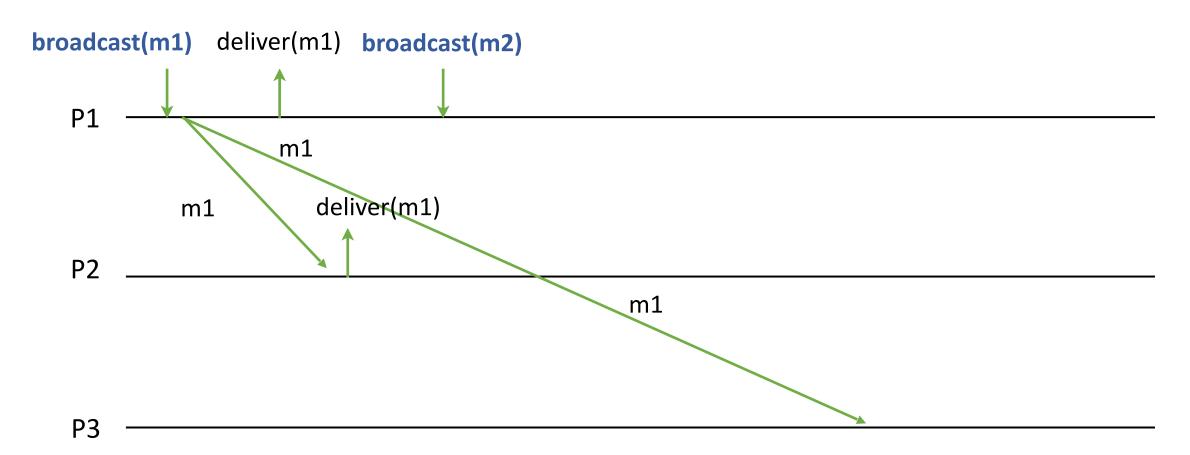


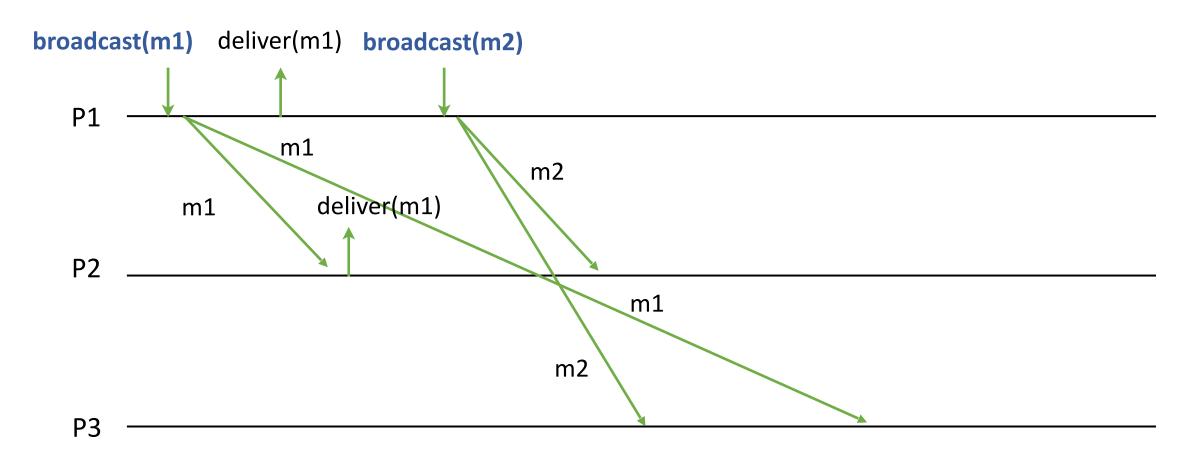
P2

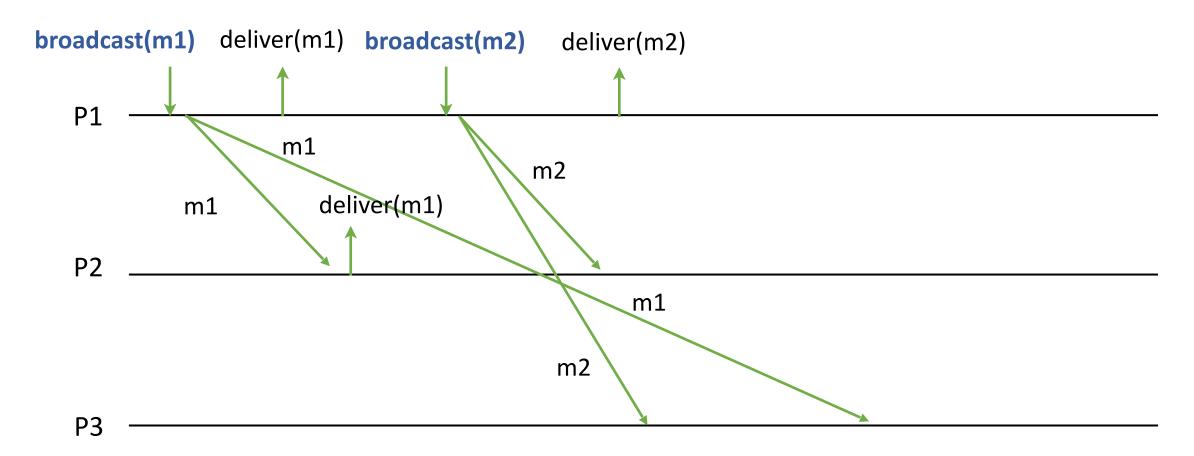


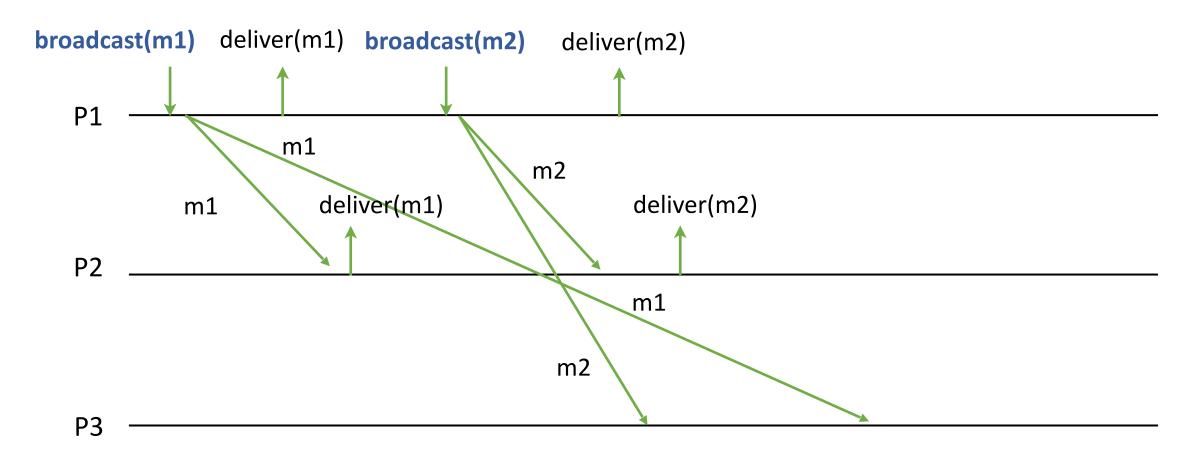


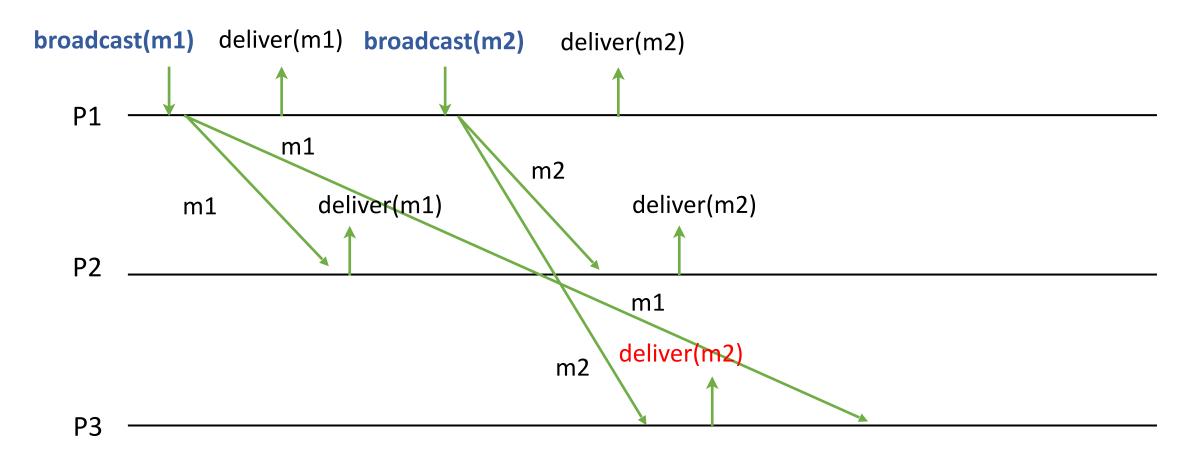


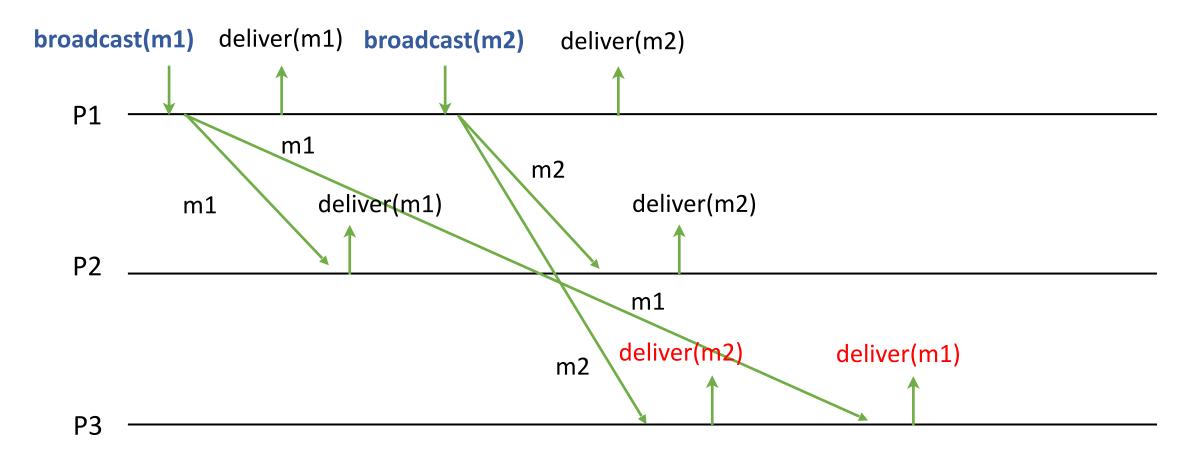




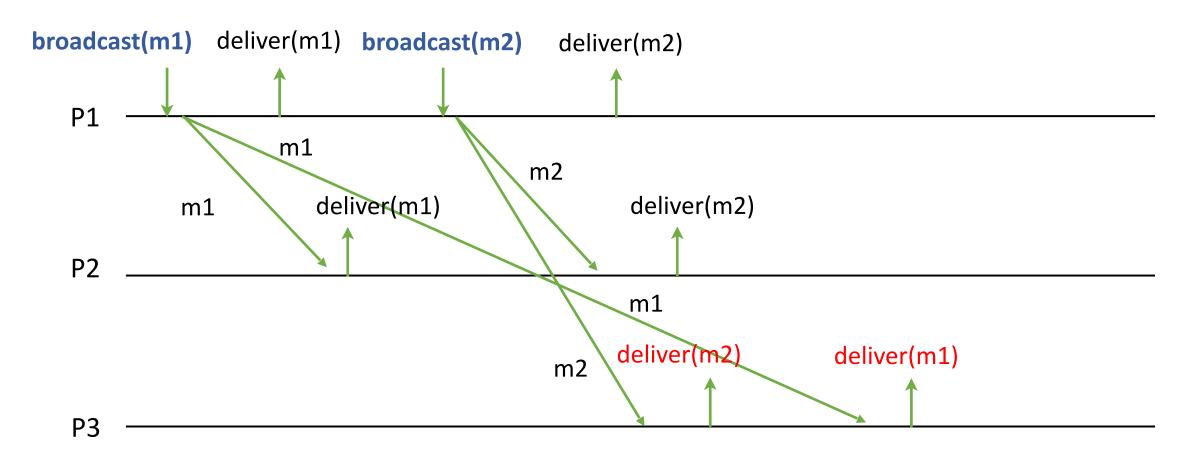




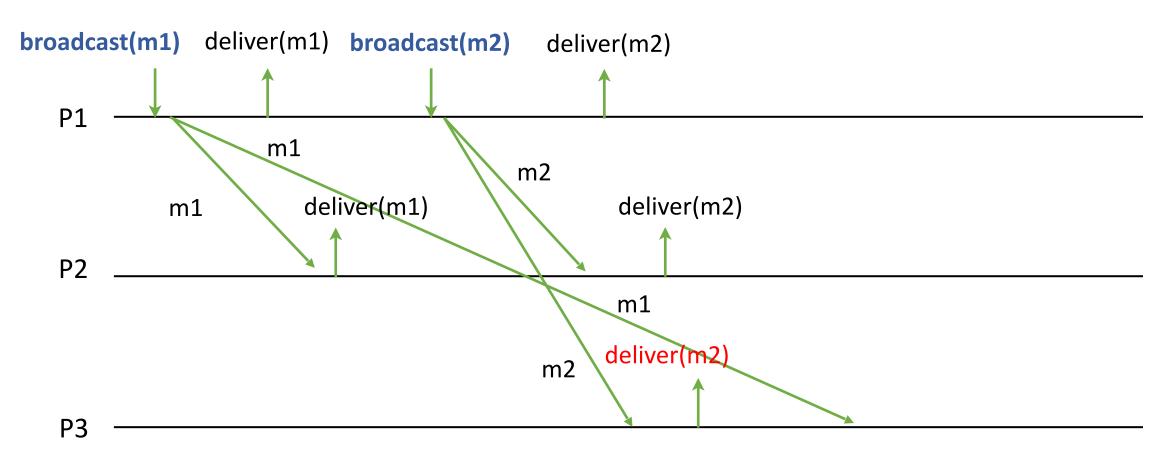




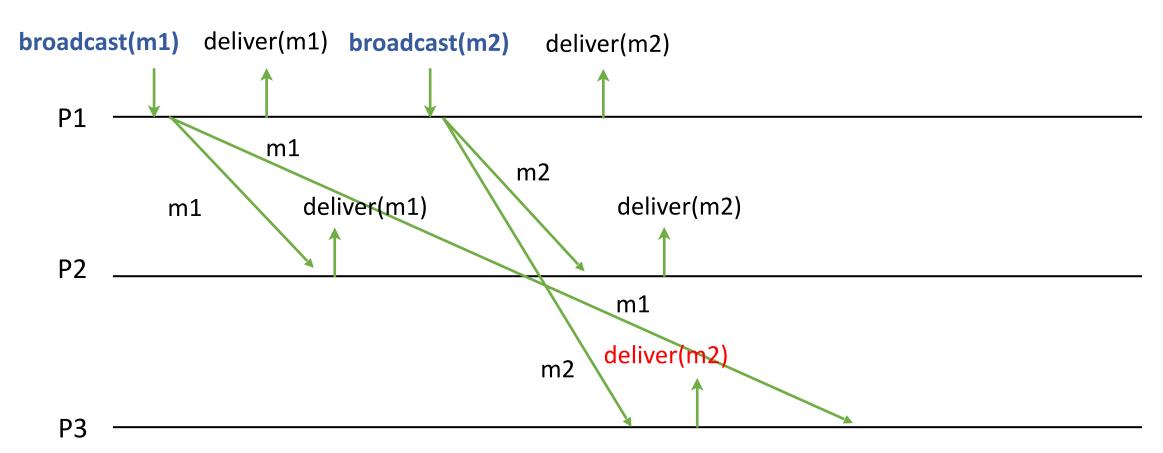
If a process pi broadcasts m1 before broadcasting m2 then m1 < m2.



FIFO order of p1, m1 < m2, is not preserved.



If a process pi broadcasts m1 before broadcasting m2 then m1 < m2.



m2 delivered but m1 not delivered. FIFO order of p1, m1 < m2, is not preserved. Let m1 and m2 be any two messages. m1 < m2 (m1 is causally before m2, or m2 depends on m1) iff

• FIFO order:

A process pi broadcasts m1 before broadcasting m2.

• InOut order:

A process pi delivers m1 and then broadcasts m2.

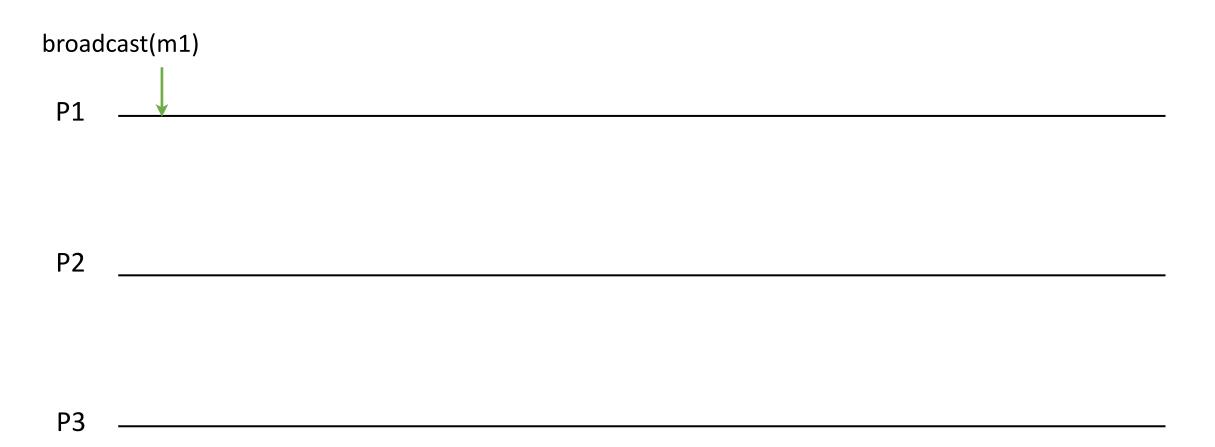
• ...

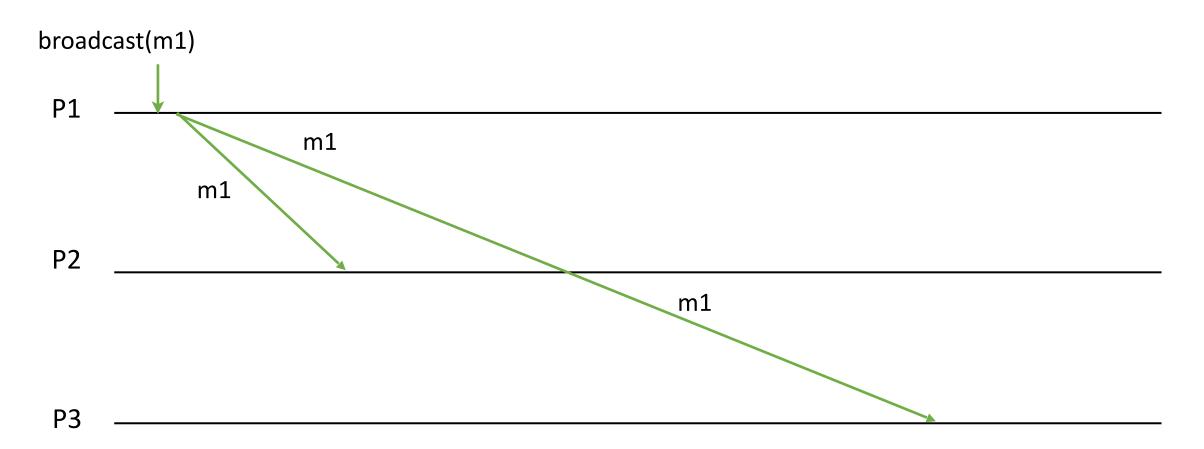
Example 2: InOut Order

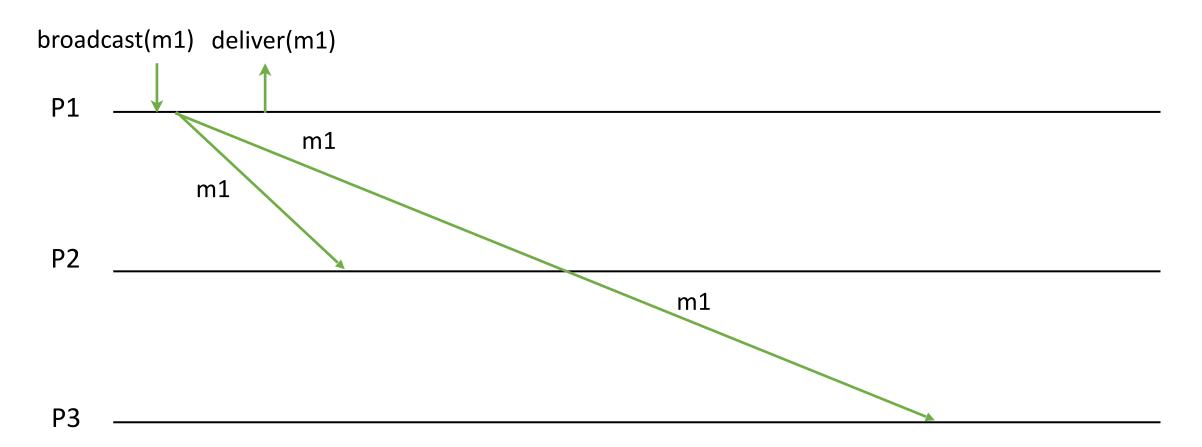
If a process pi delivers m1 and then broadcasts m2 then then m1 < m2.

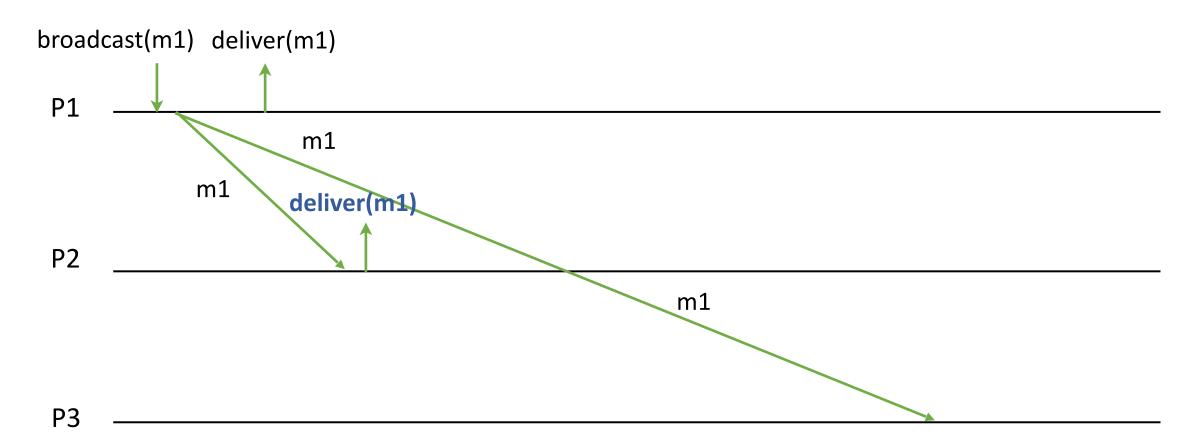
Ρ1

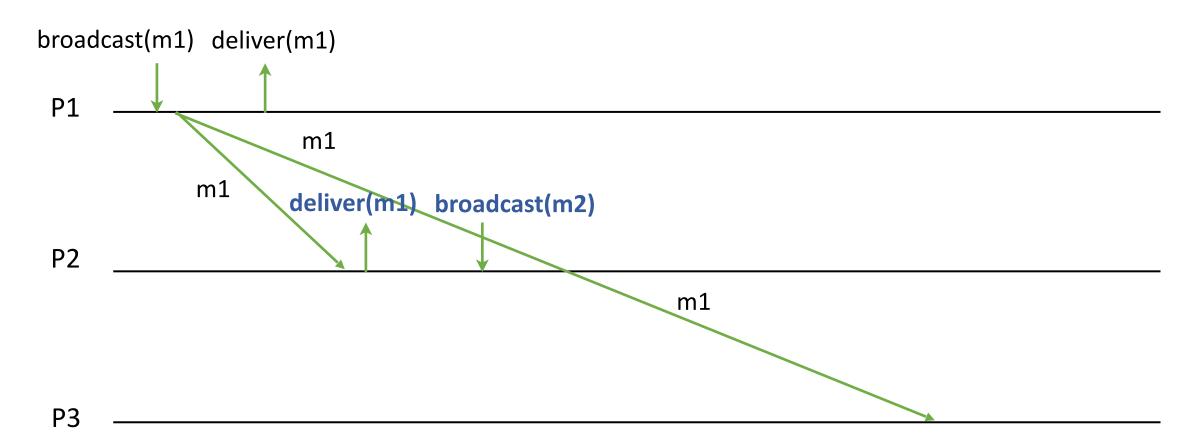
P2

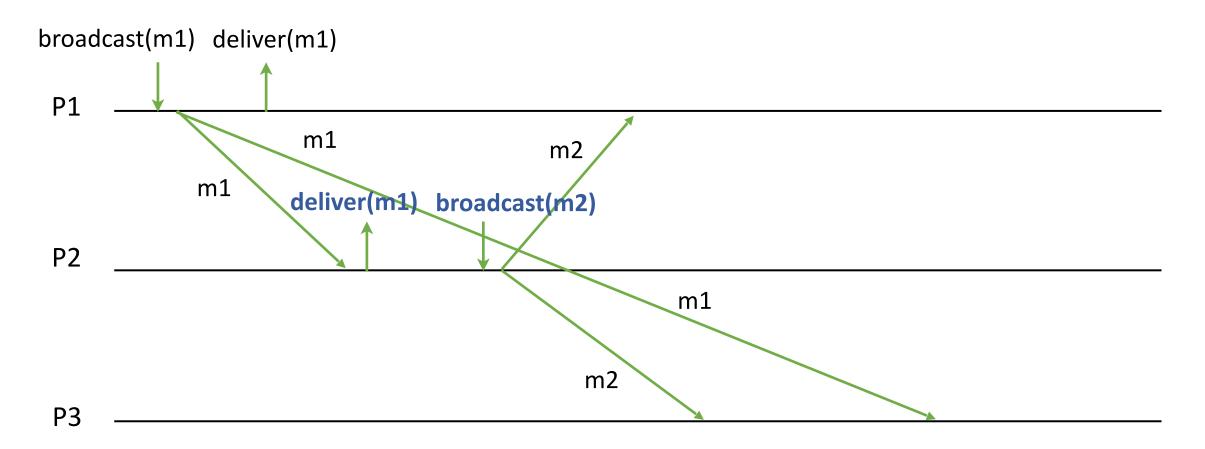


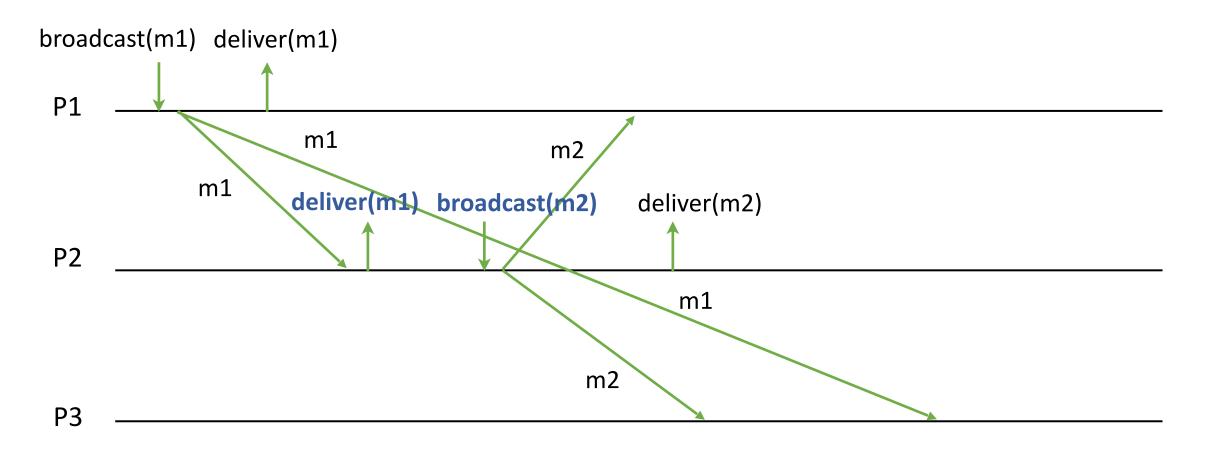


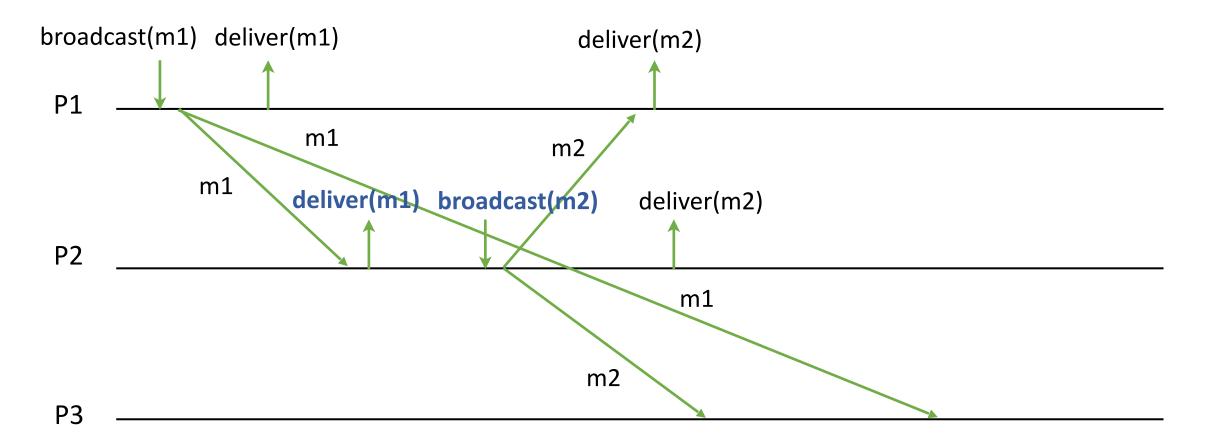


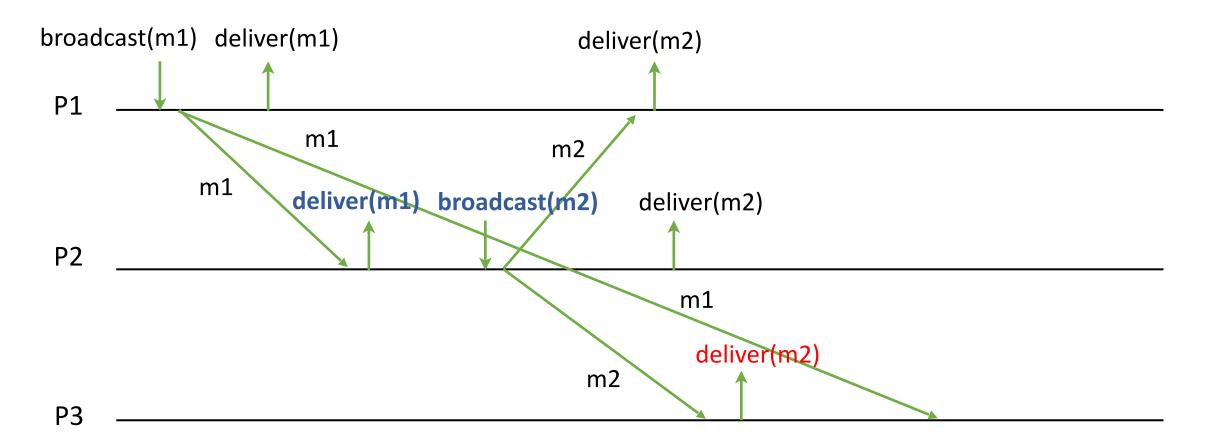


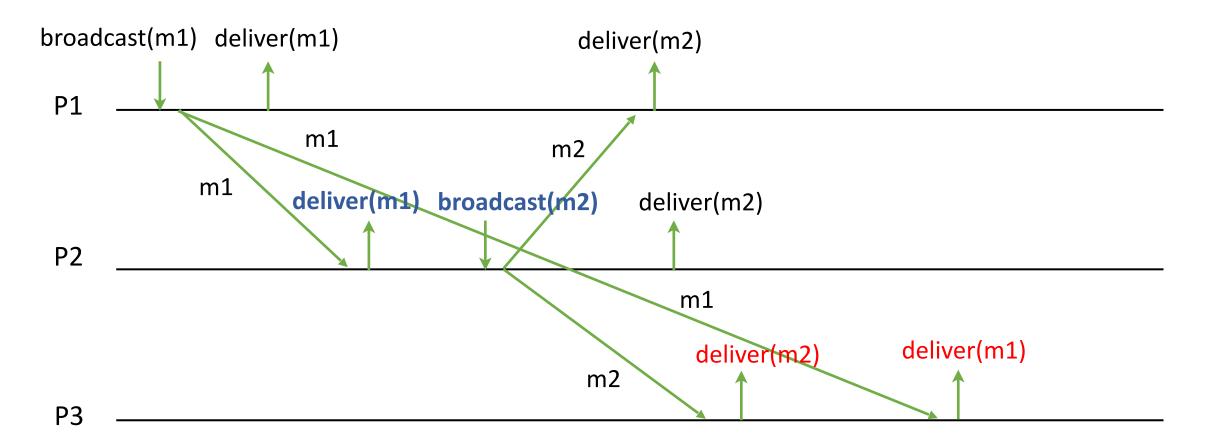


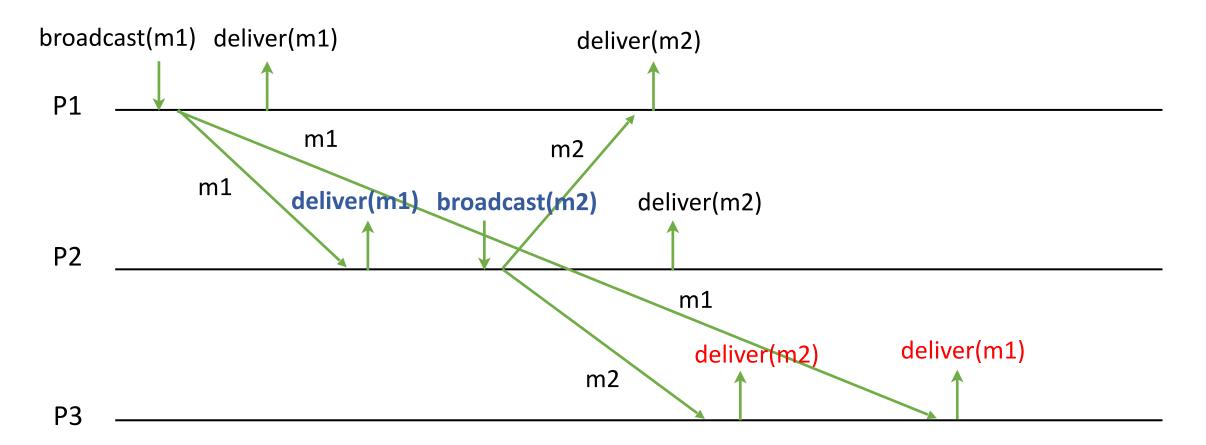












Local order of p2, m1 < m2, is not preserved.

Causal Relation (Dependency)

Let m1 and m2 be any two messages. m1 < m2 (m1 is causally before m2, or m2 depends on m1) iff

• FIFO order:

A process pi broadcasts m1 before broadcasting m2.

• InOut order:

A process pi delivers m1 and then broadcasts m2.

• Transitivity:

There is a message m3 such that m1 < m3 and m3 < m2.

• Events

- Request: <broadcast (m)>
- Indication: <deliver (src, m)>

also called ucbBroadcast and ucbDeliver.

• Properties:

- URB1, URB2, URB3, URB4 +
- CO

Overview

- Motivation: why causal broadcast?
- Properties of causal broadcast
- Protocols

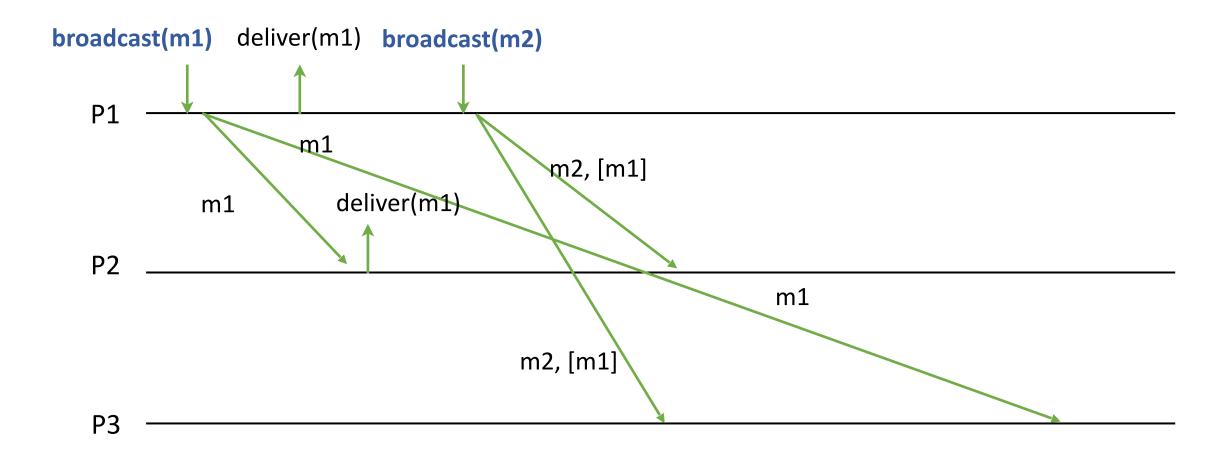
Protocols

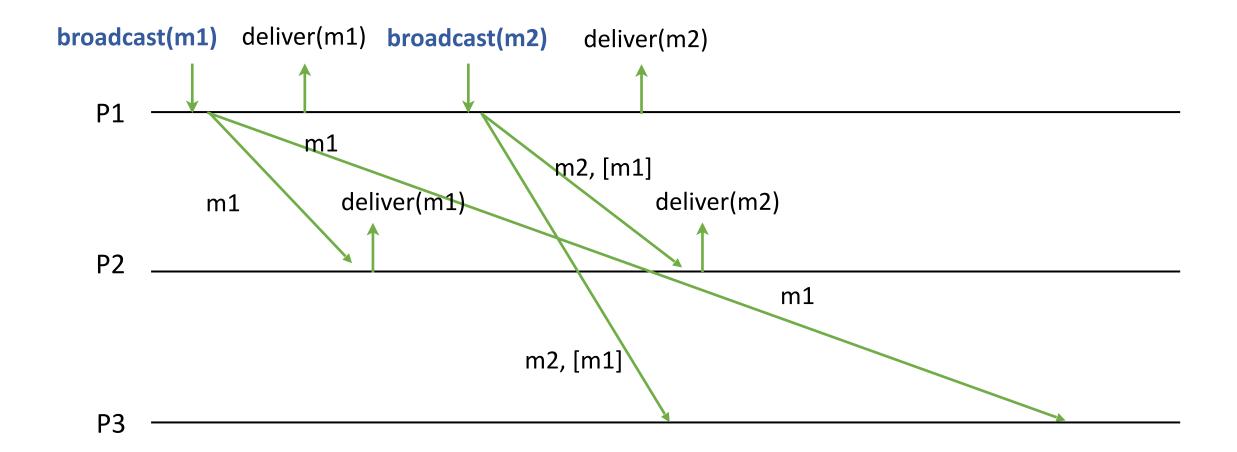
How do we preserve the causal order?

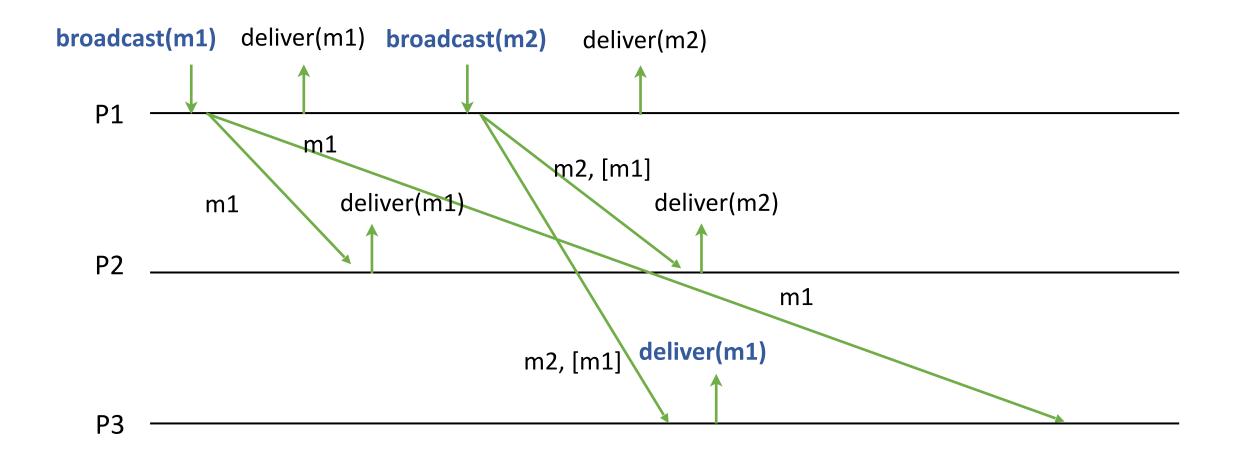
Protocol 1

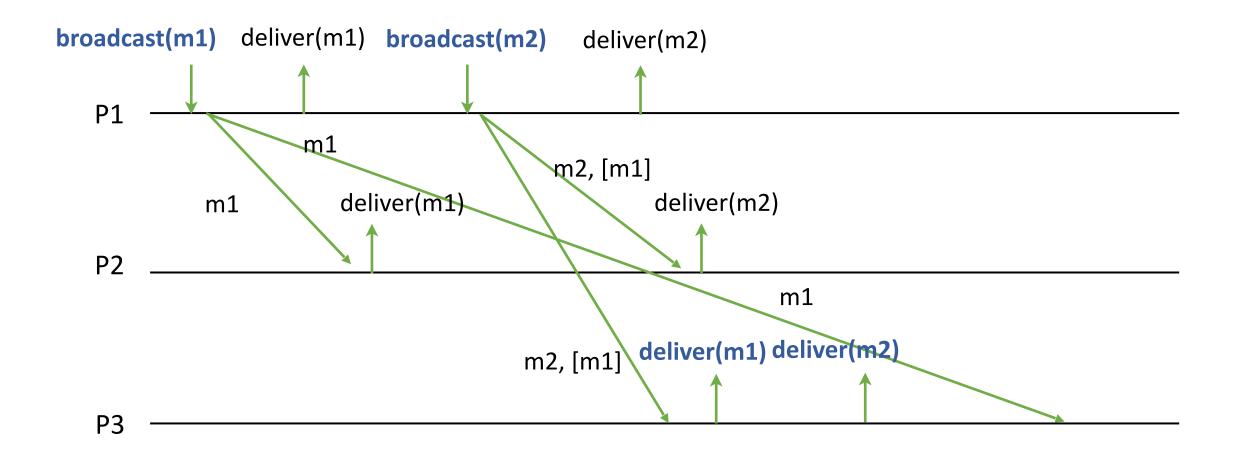


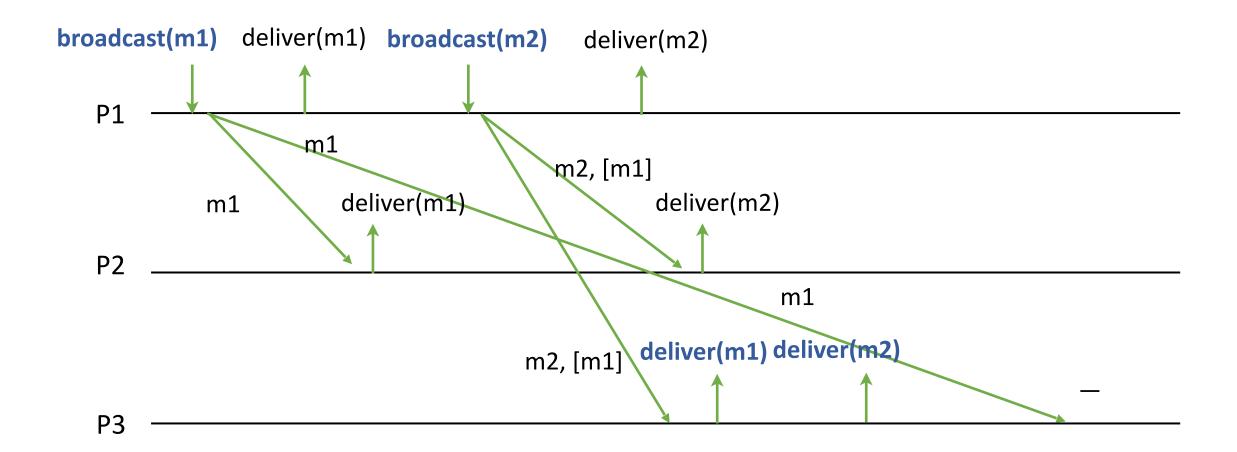
Remember the past messages and sent them together with every new message.

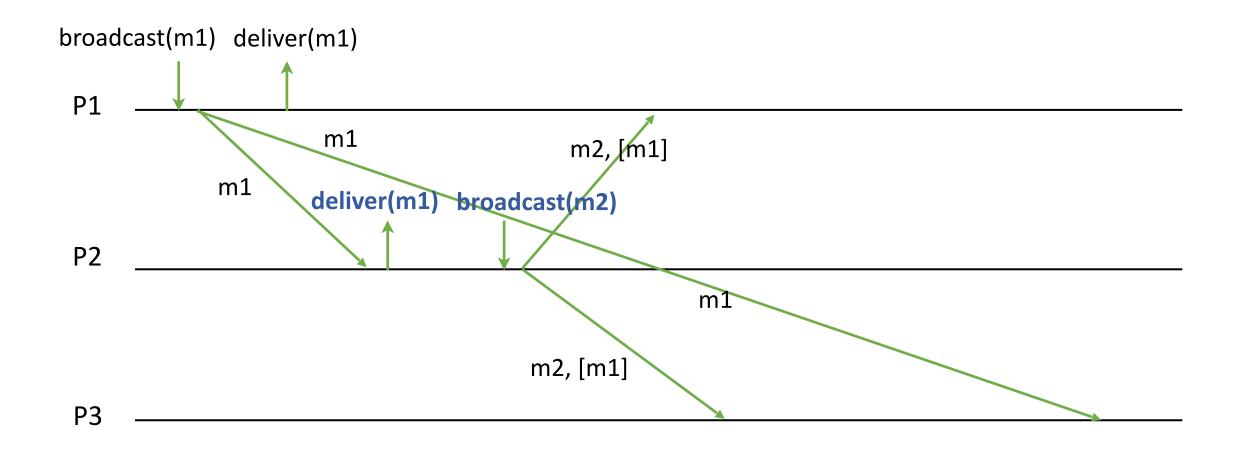


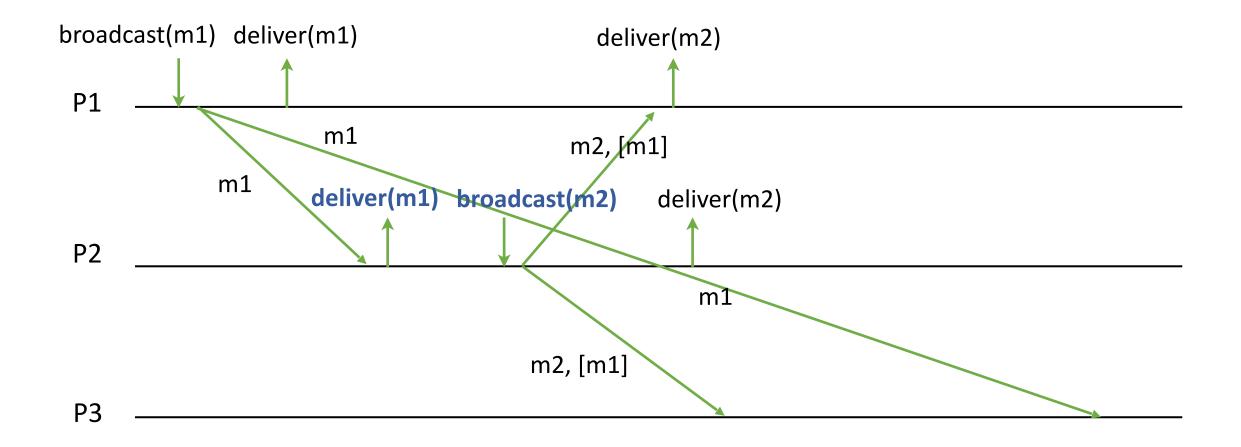


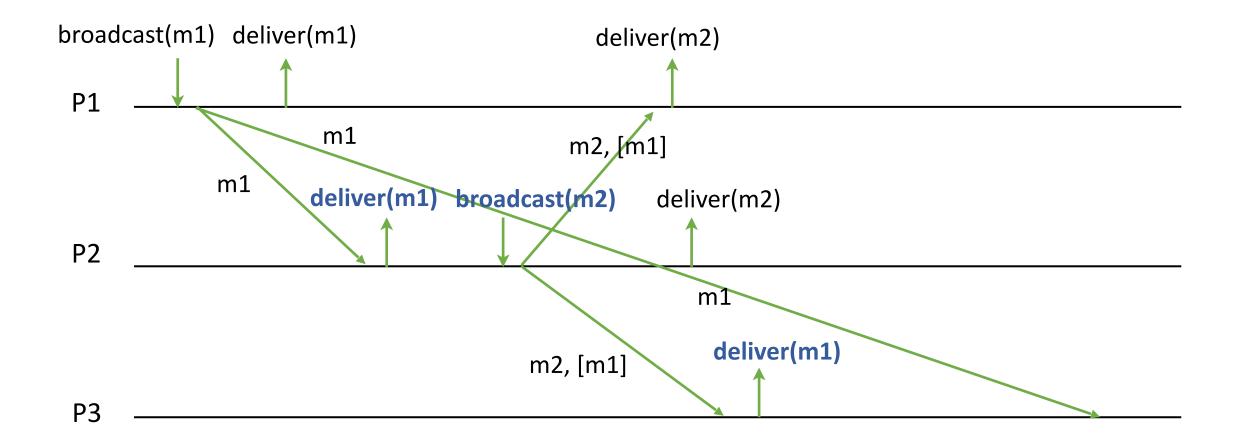


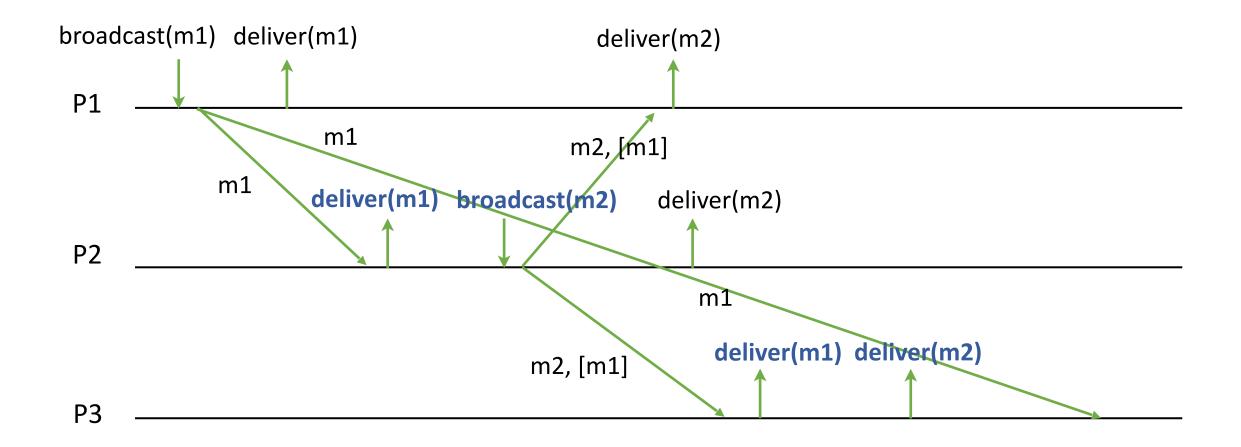


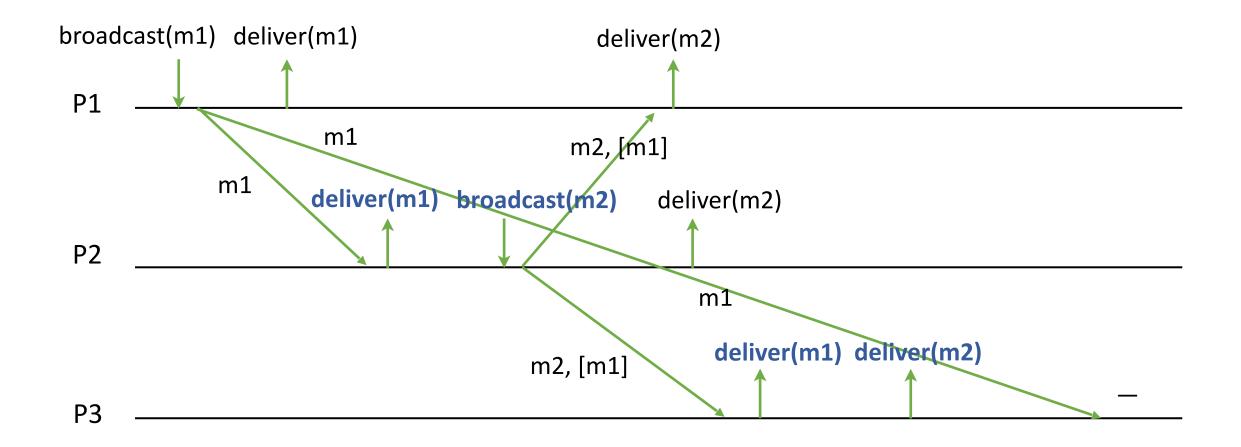












Observation

Messages that carry the past are large!

Protocol 2

Idea:



p ₁	p ₂	p 3
2	1	0

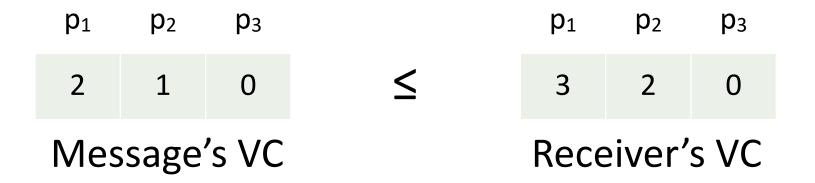
• Send the vector clock (VC) together with new messages.

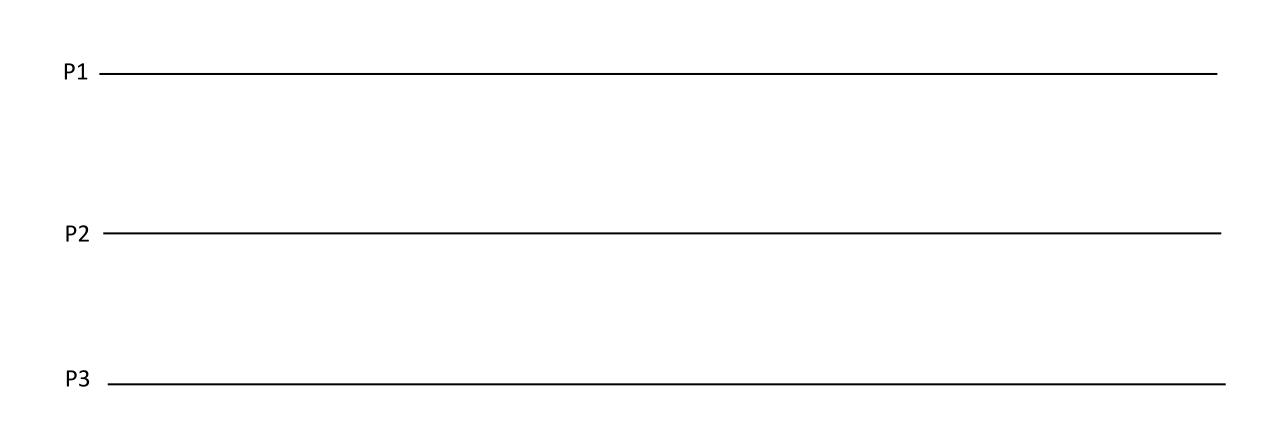
(*except for the current process that is updated with the number of broadcast messages.)

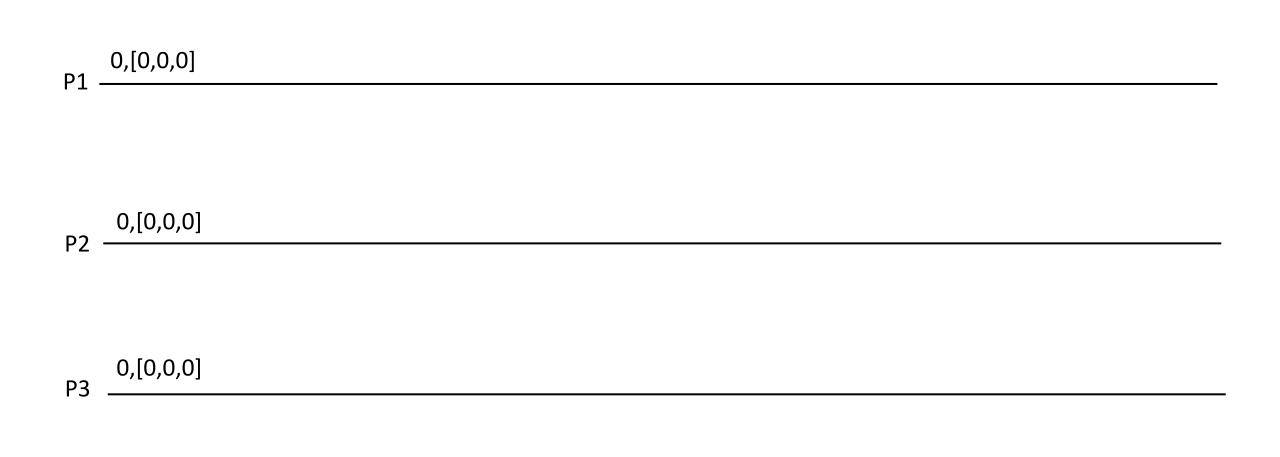
Protocol 2

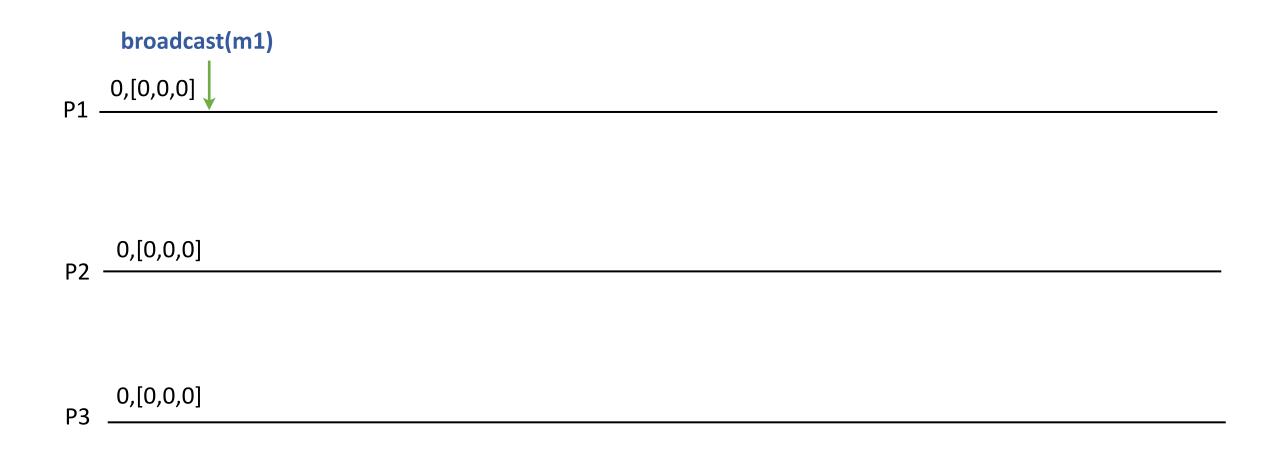


• Deliver a message only if the local vector clock is larger than the vector clock of the message.



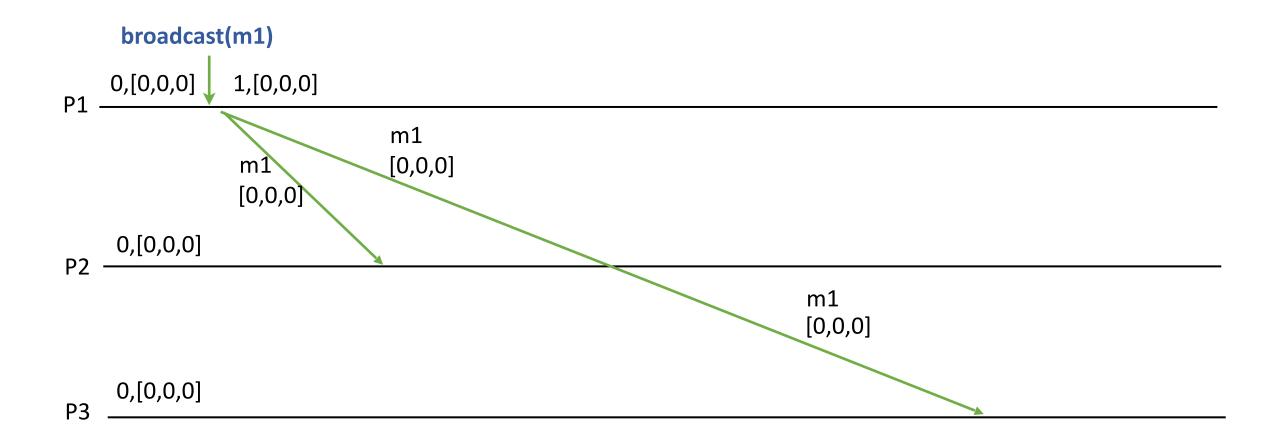


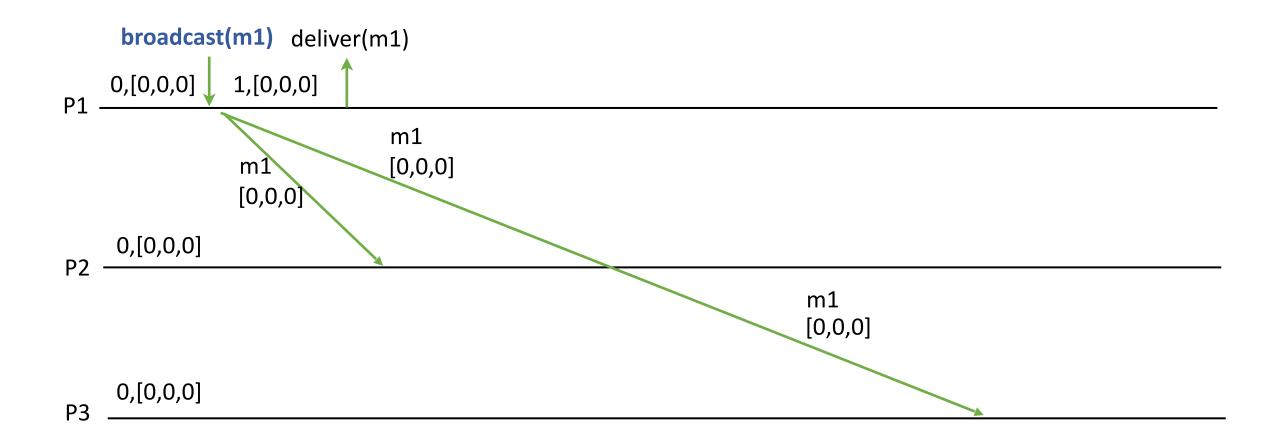


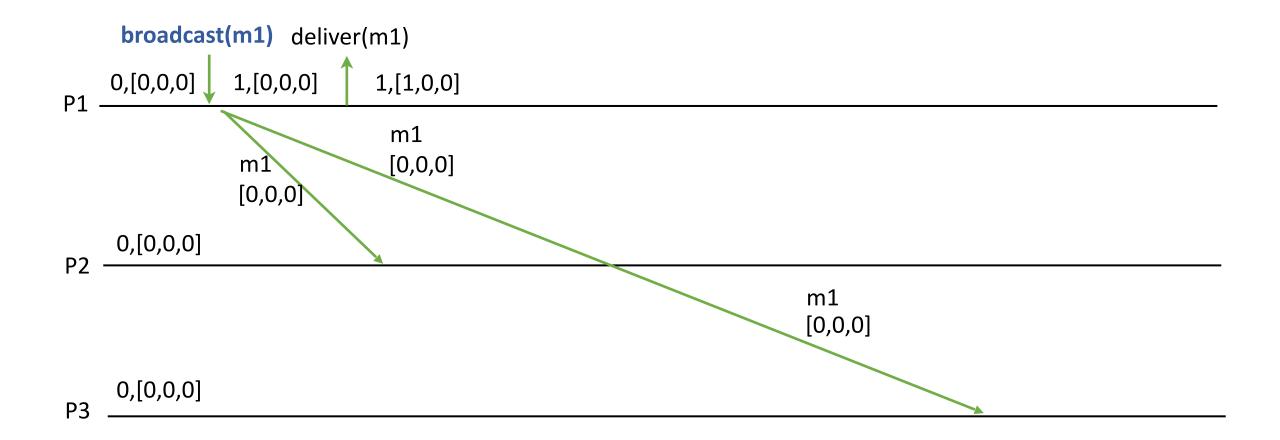


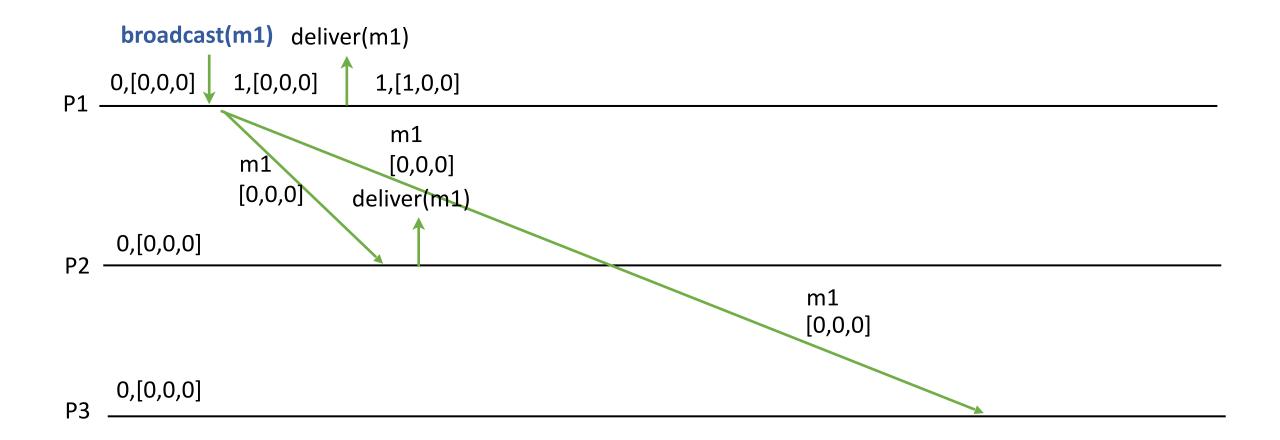


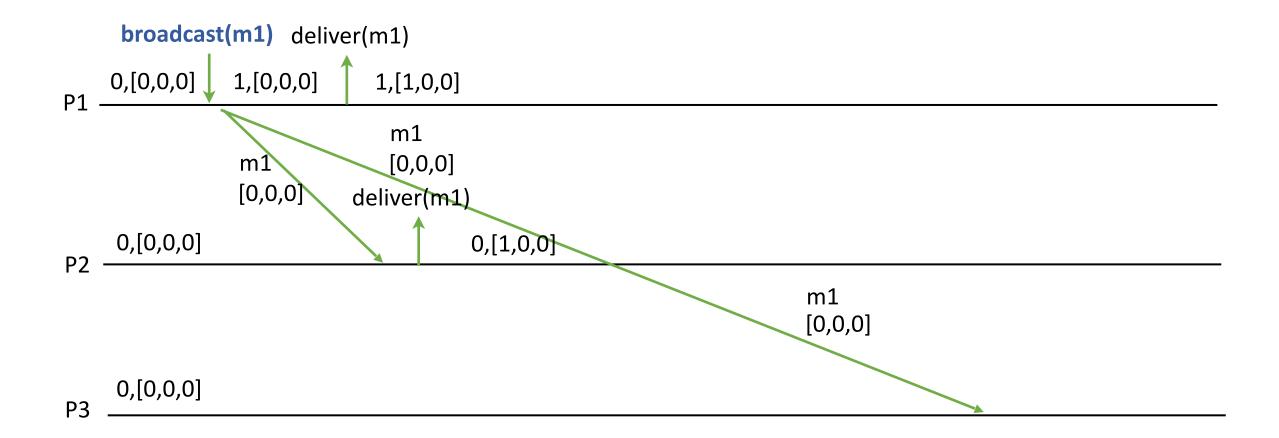
0,[0,0,0] P2

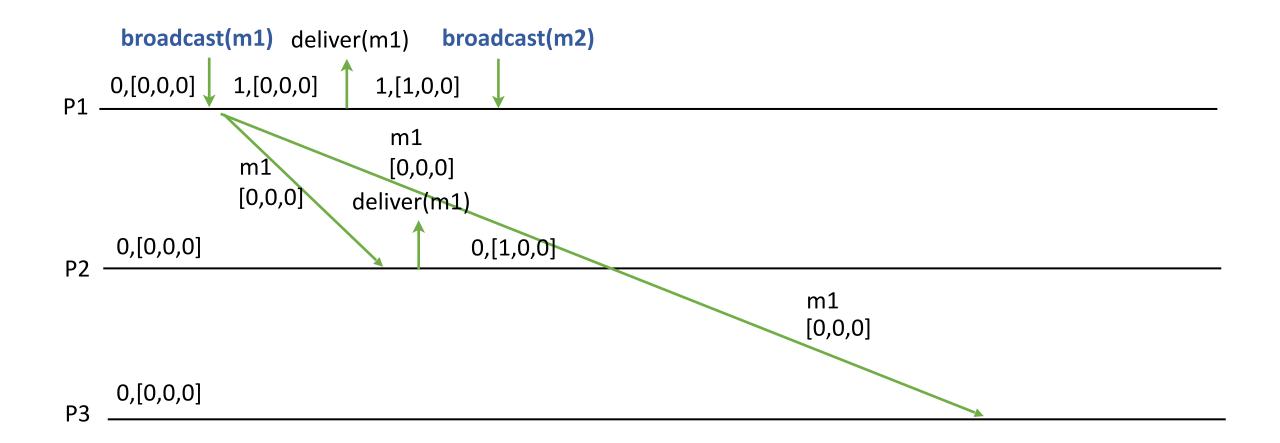


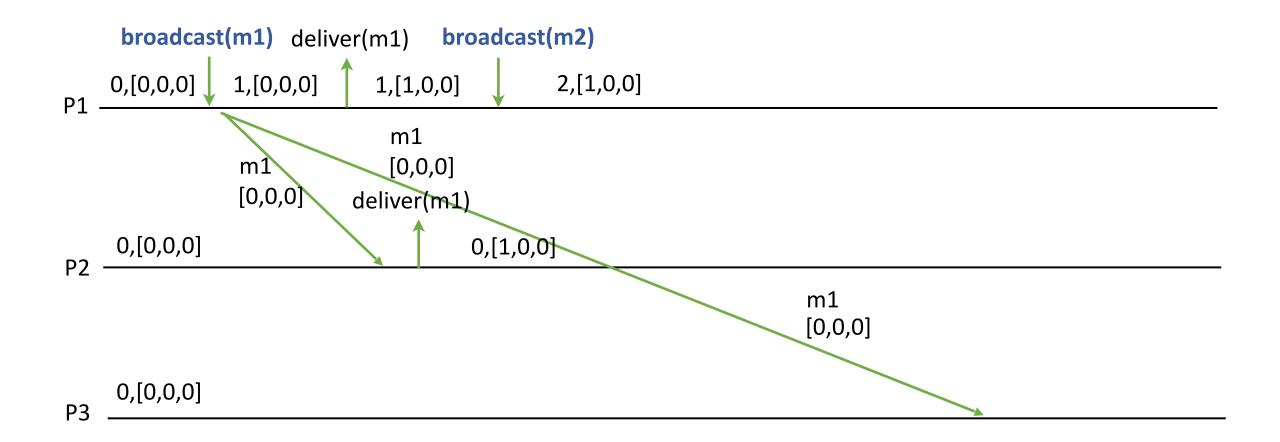


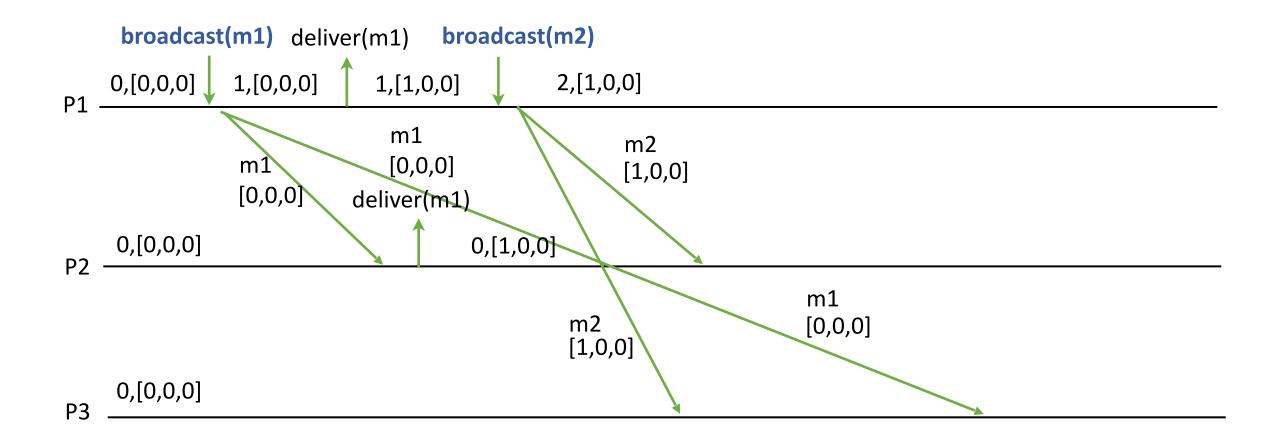


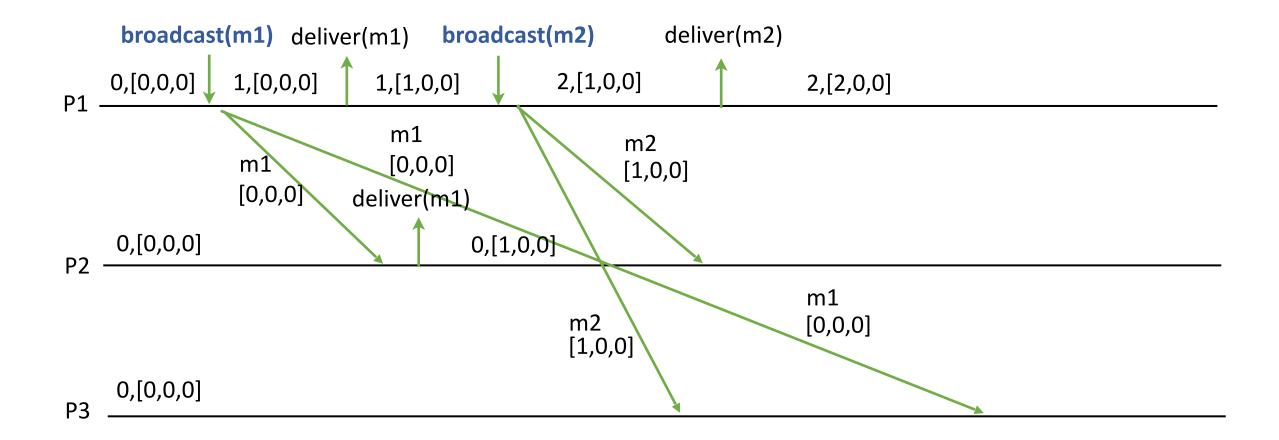


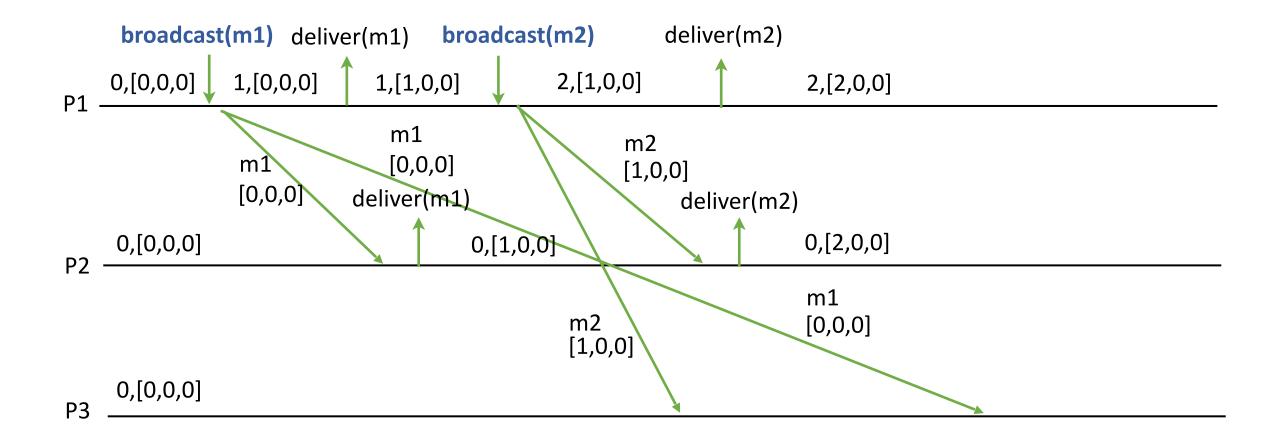


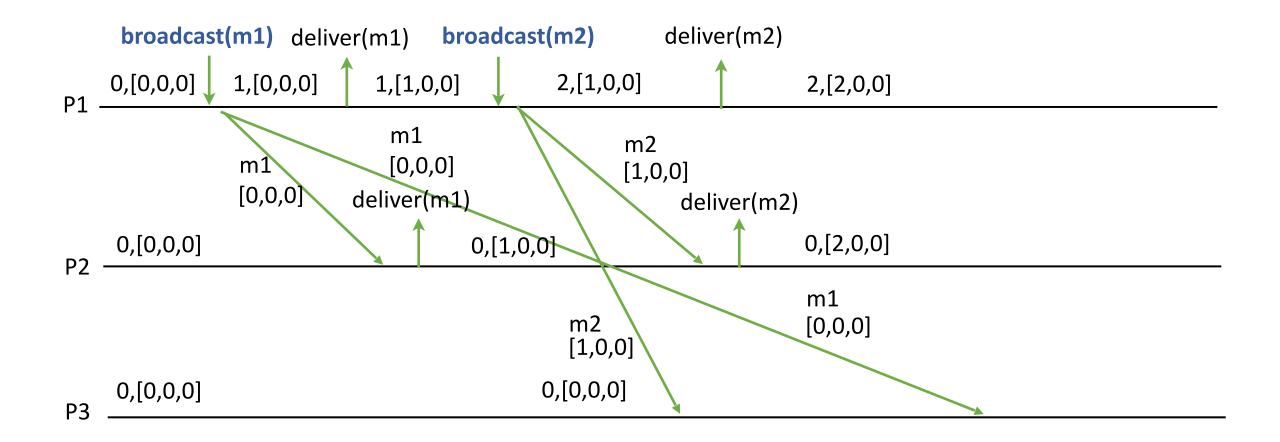


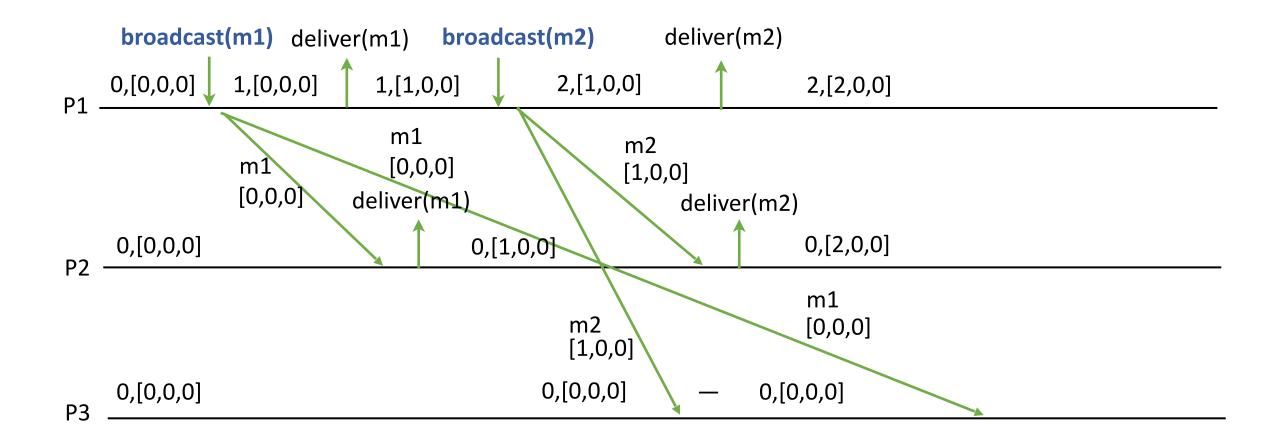


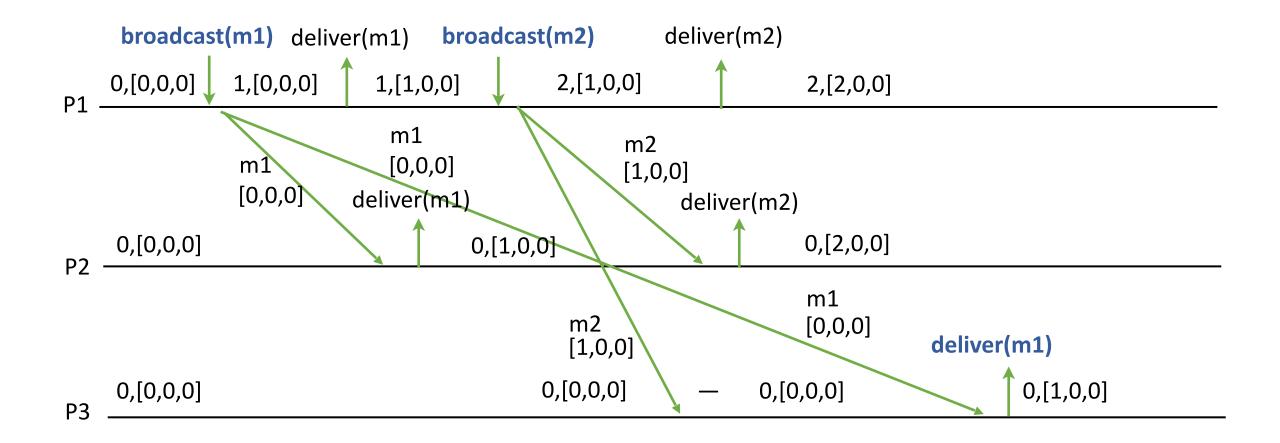


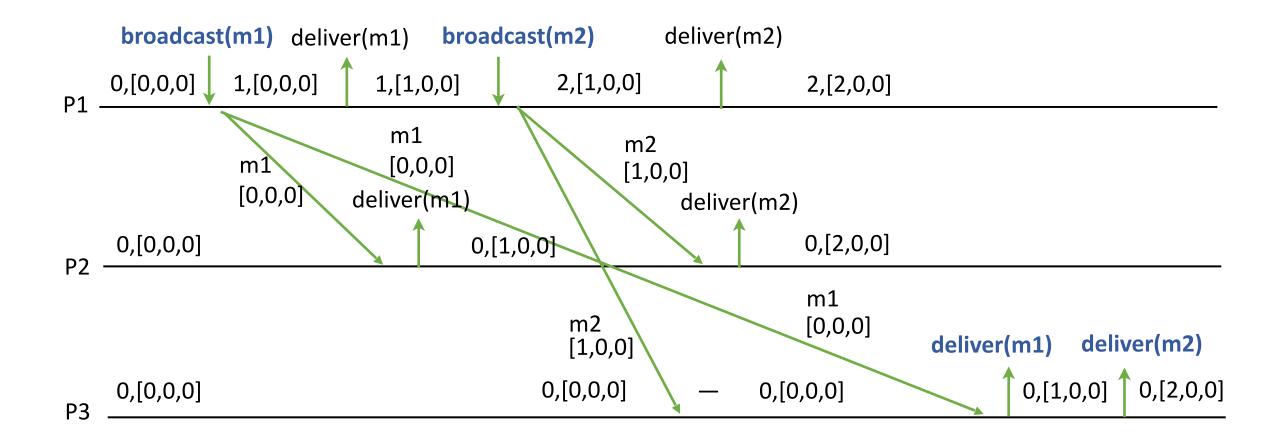




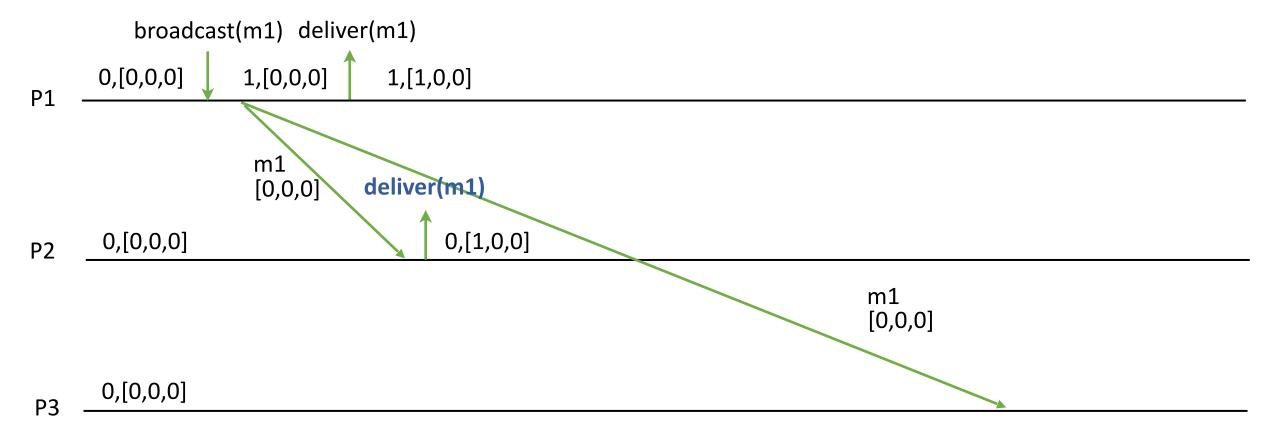


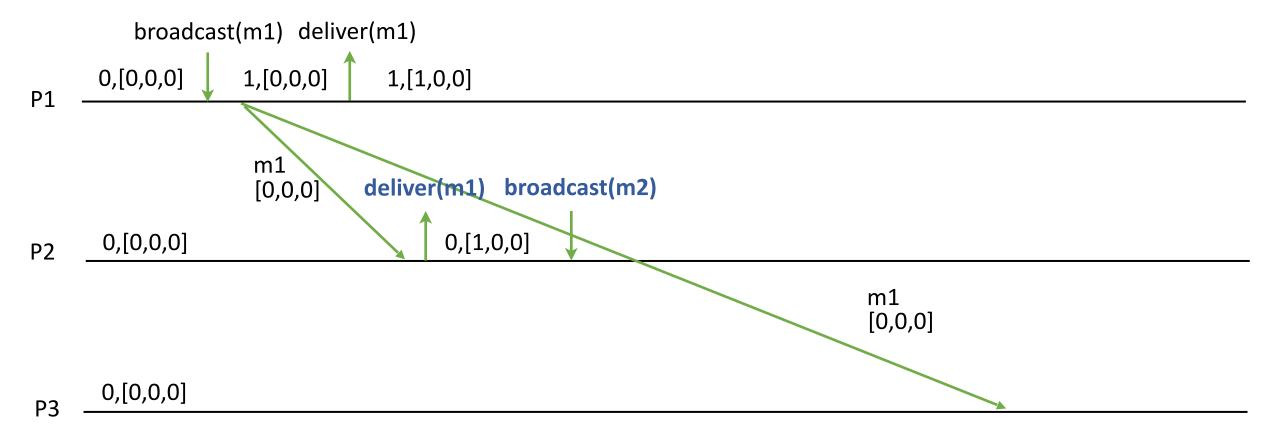


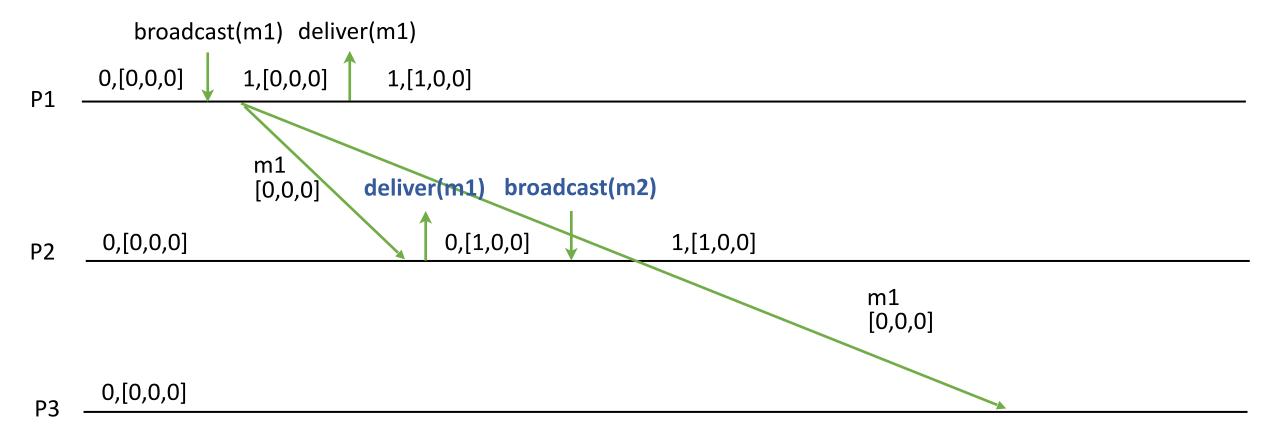


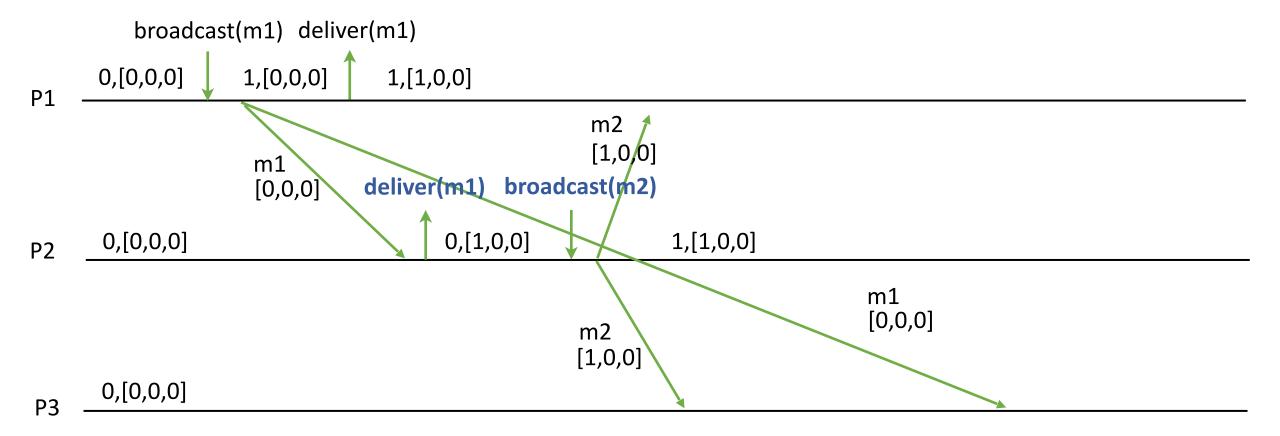


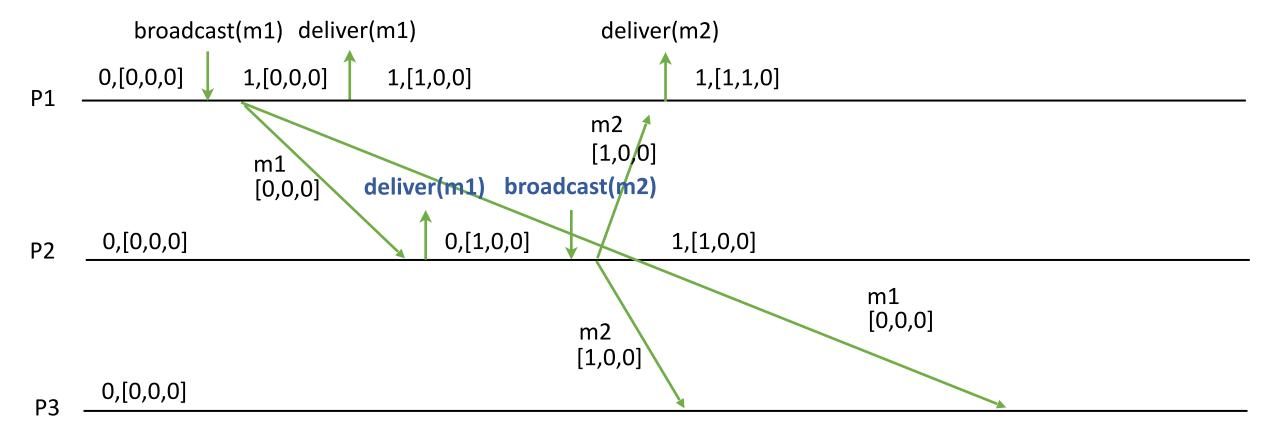
P2

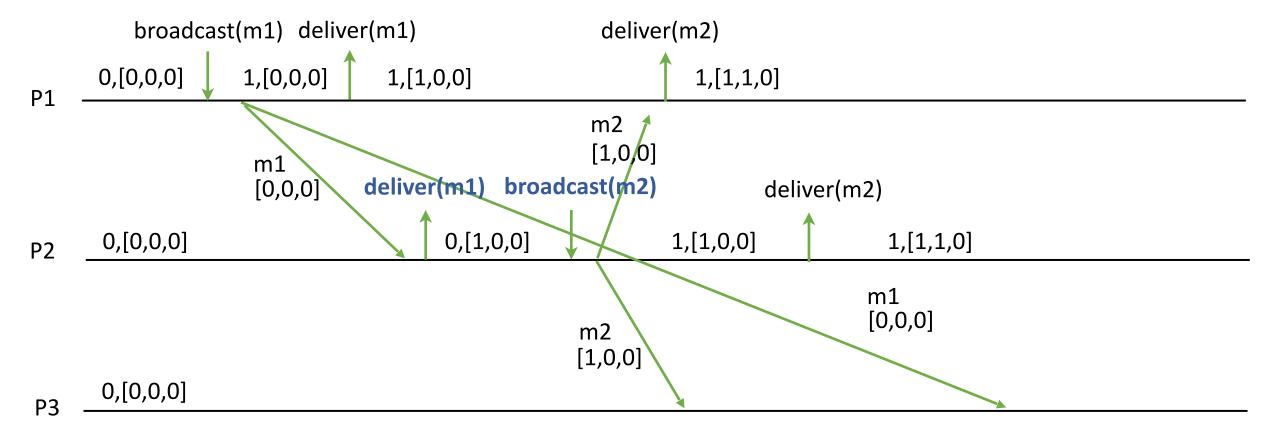


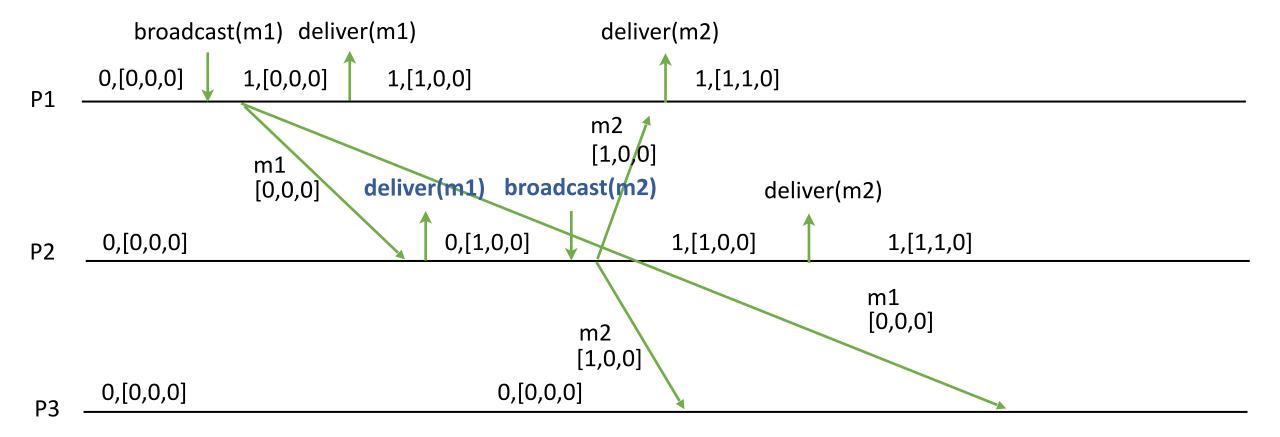


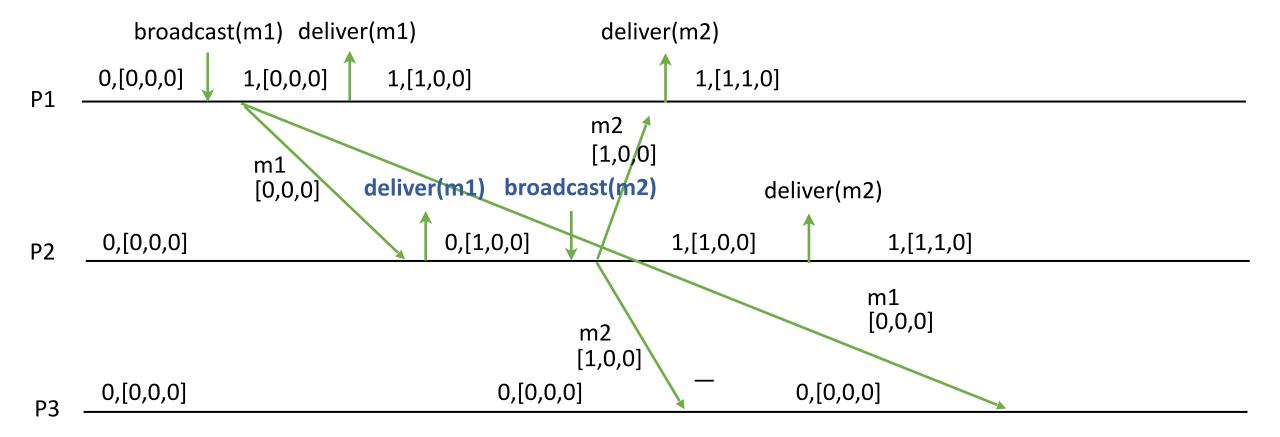


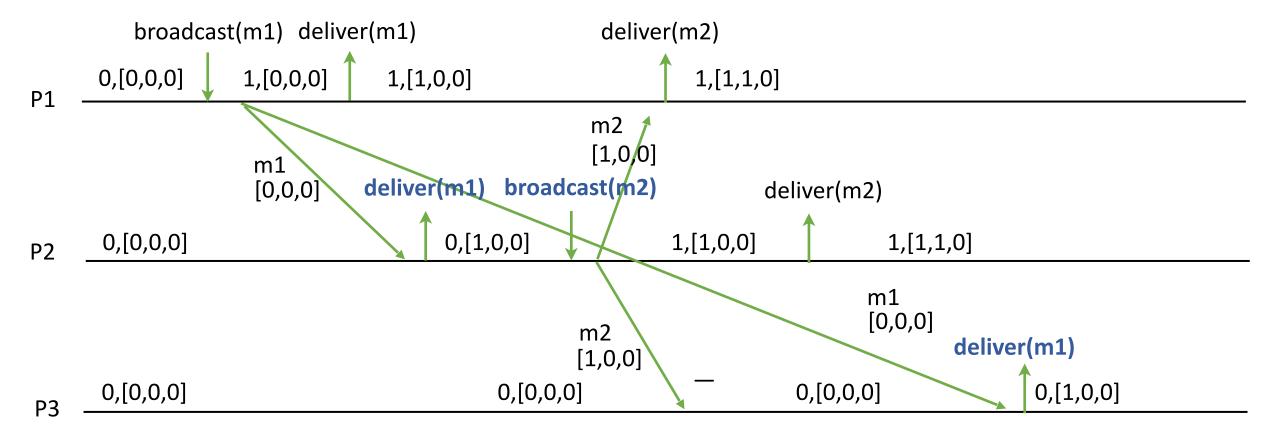


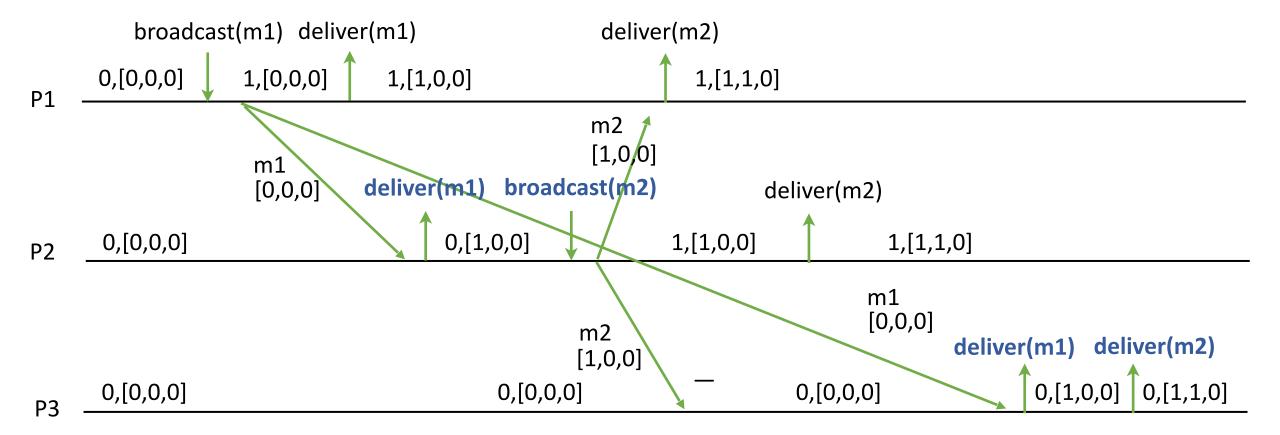


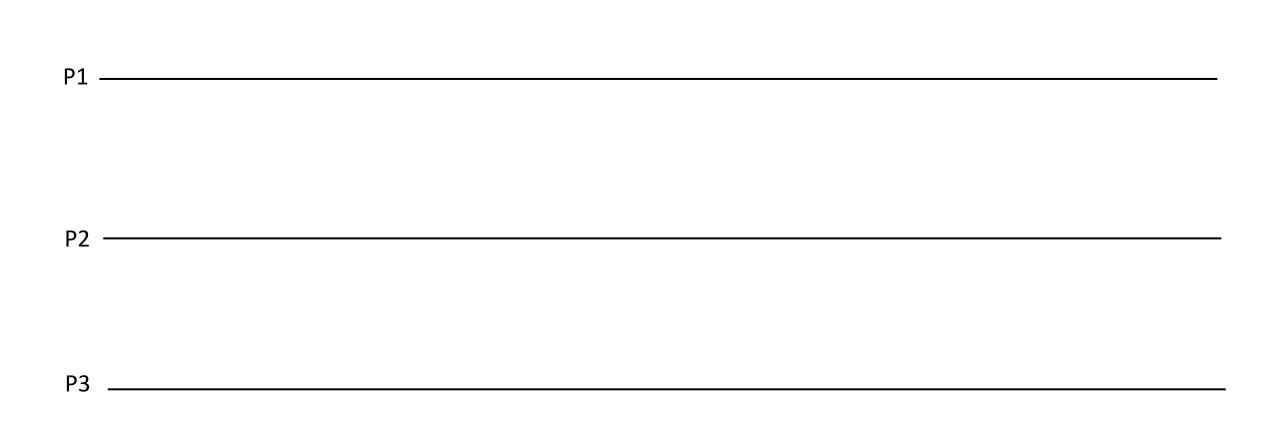


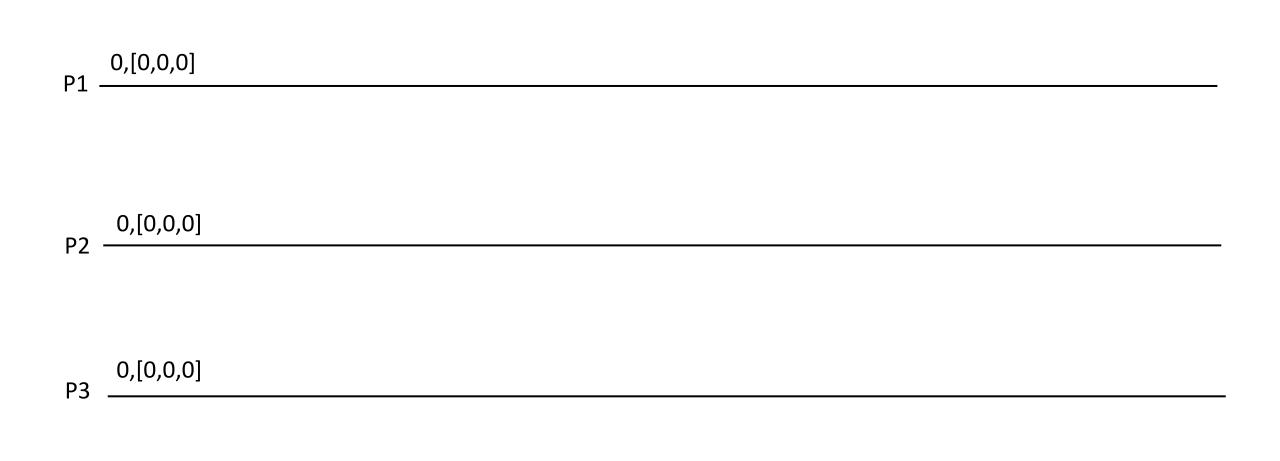


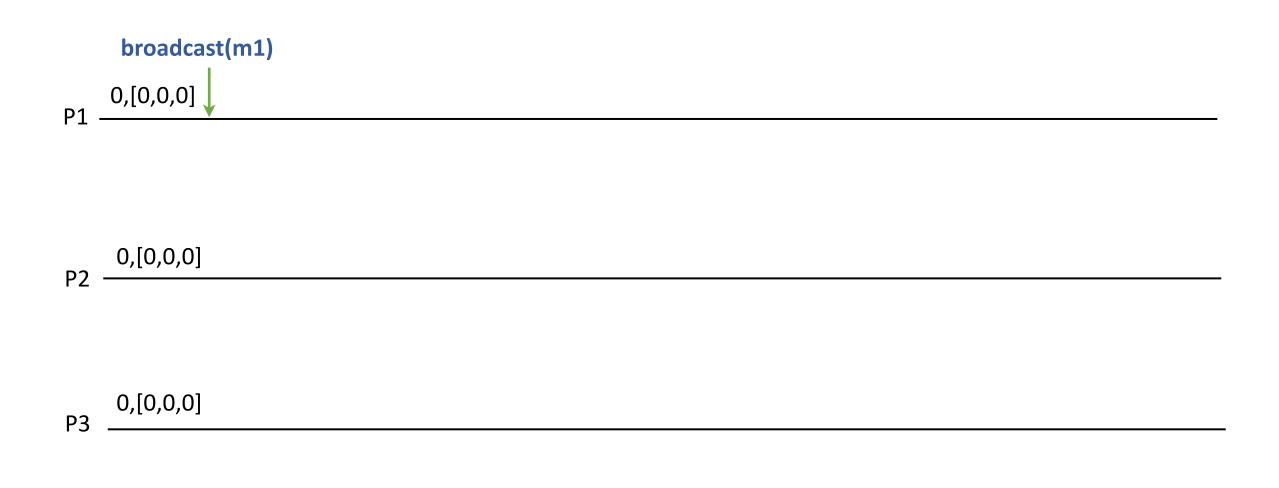




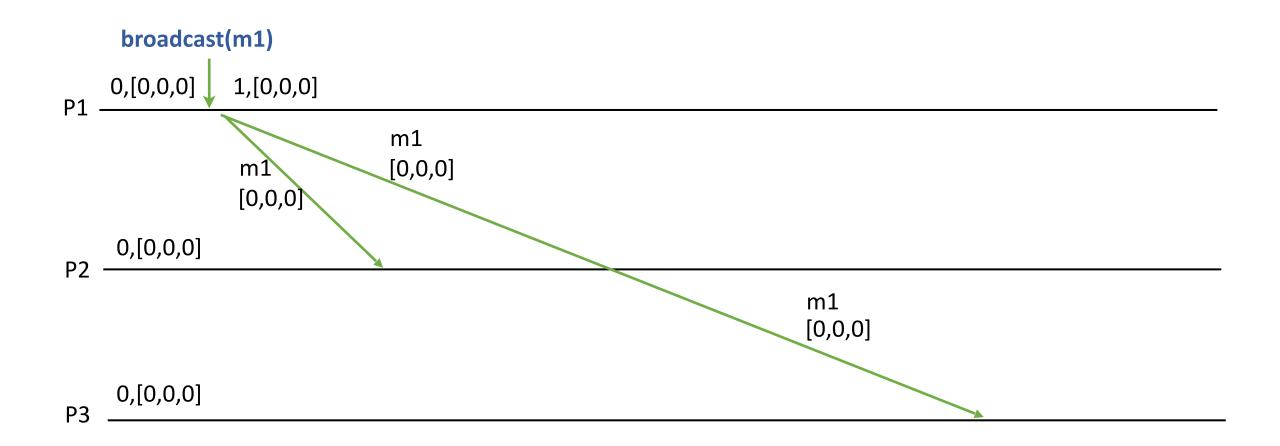


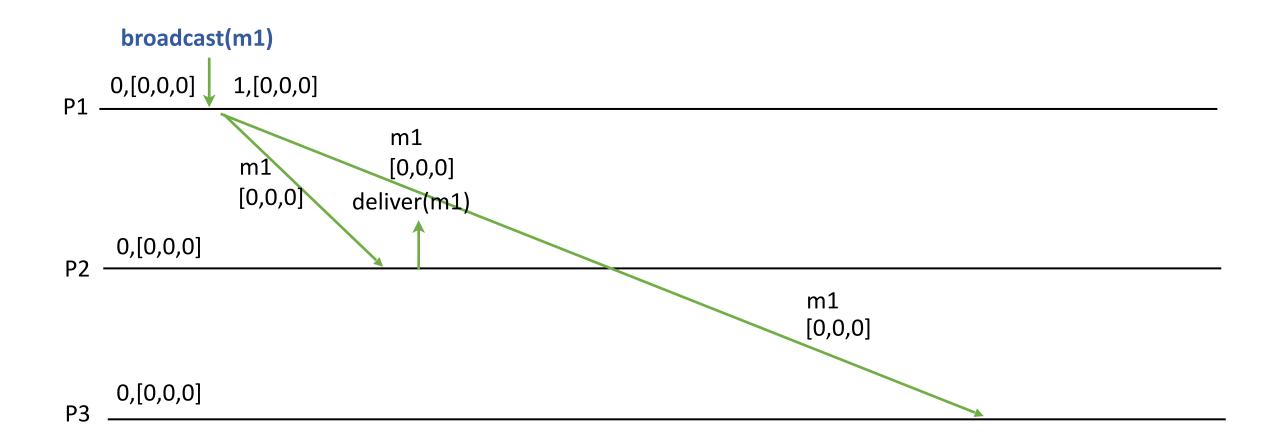


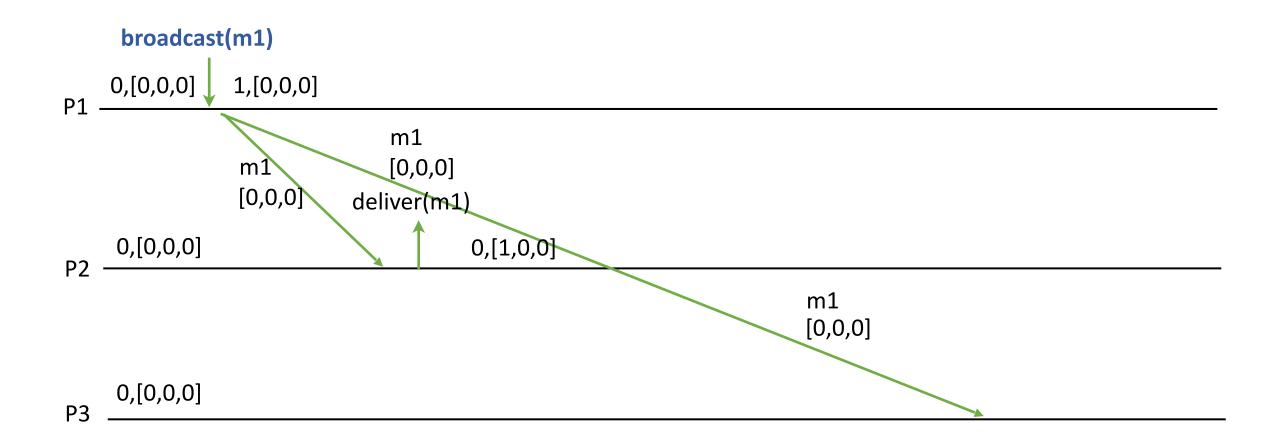


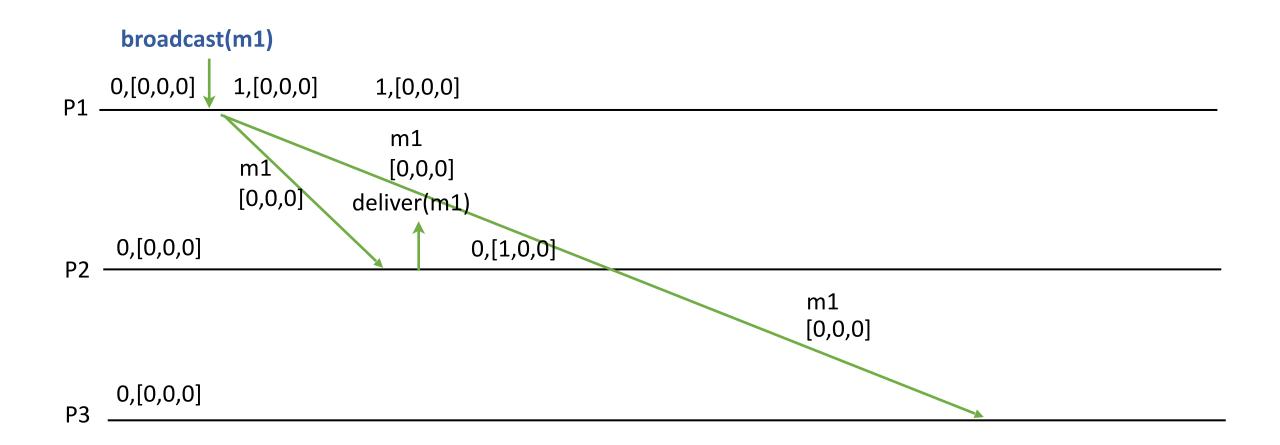


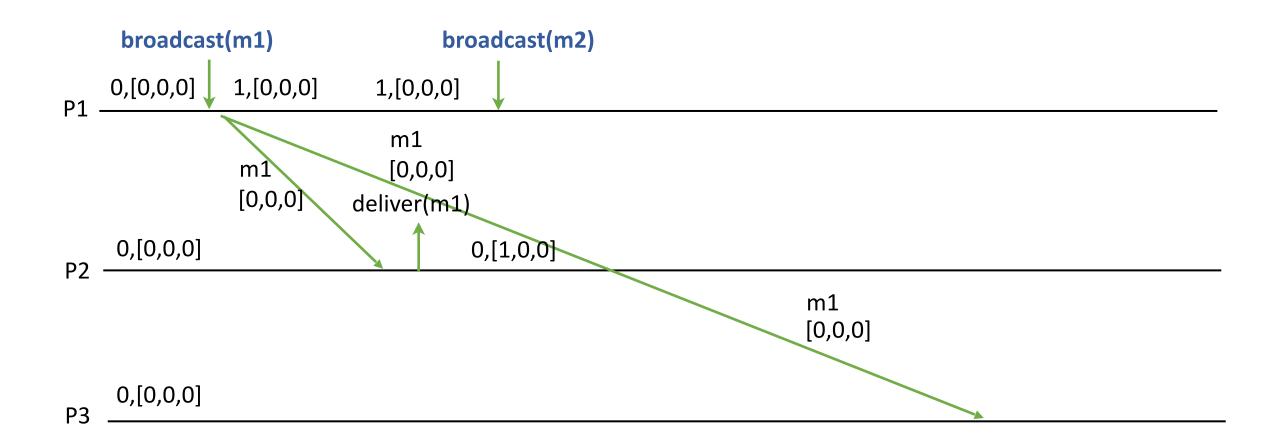


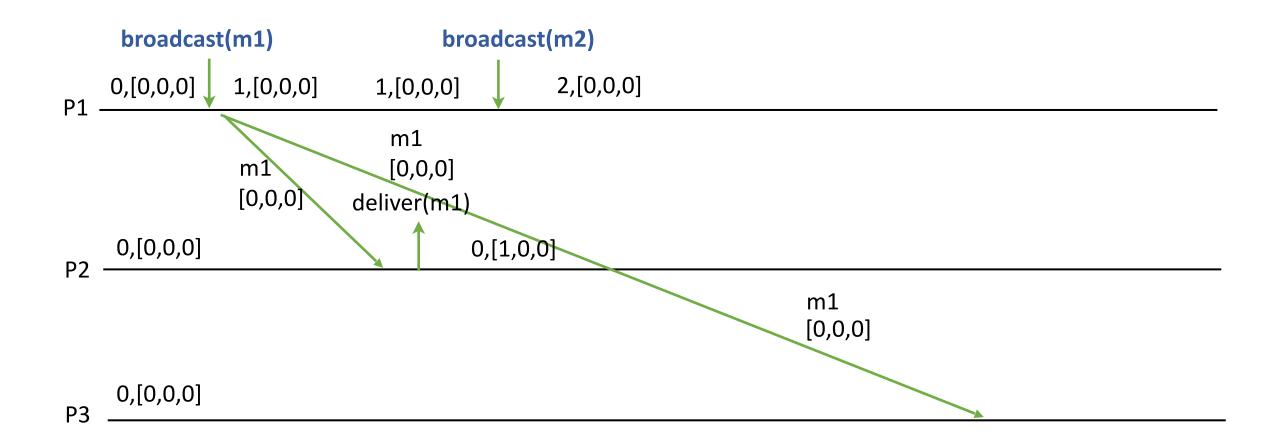


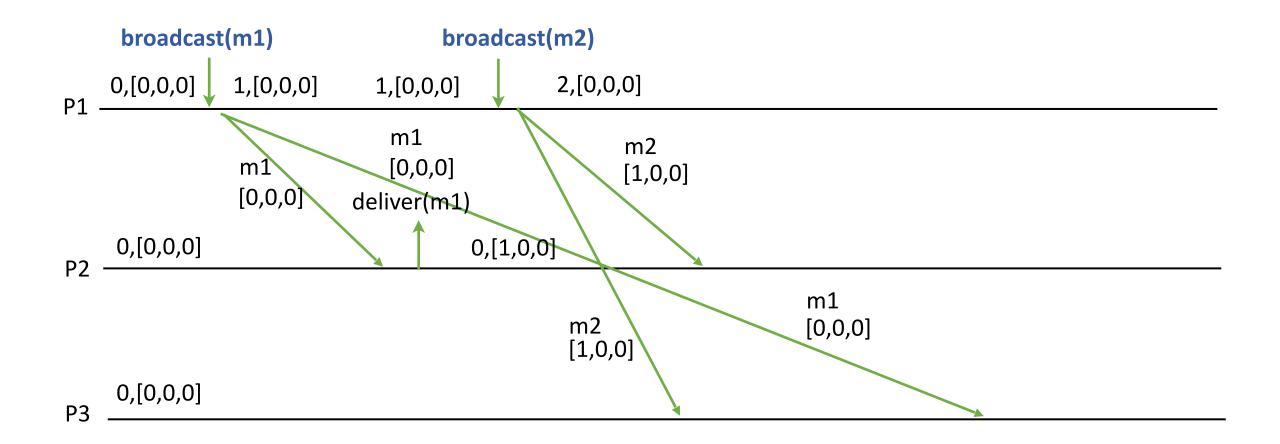


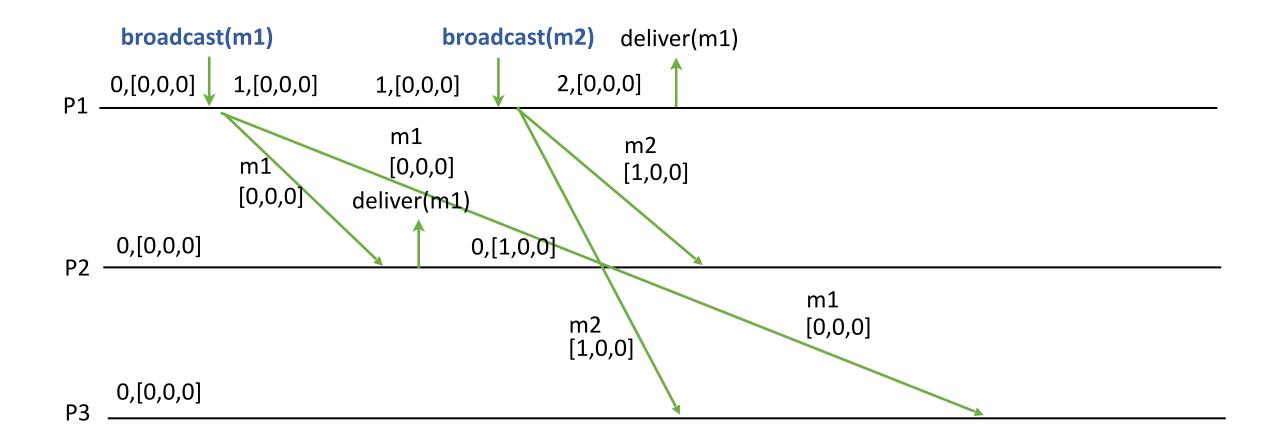


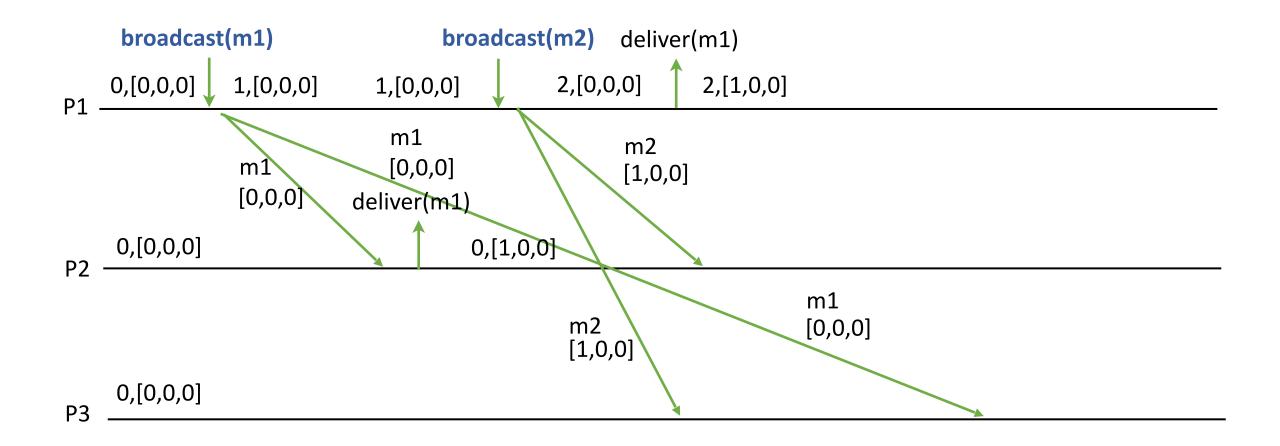


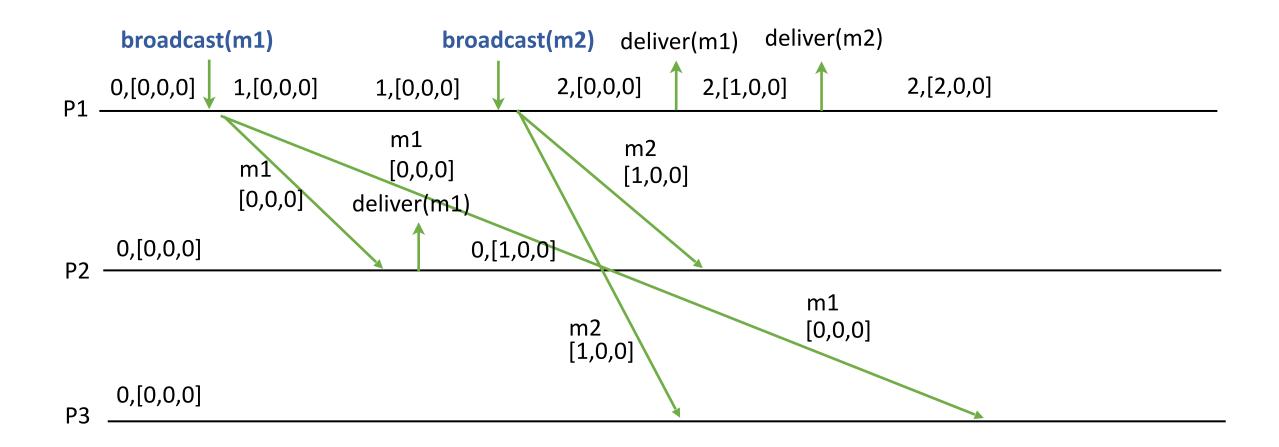


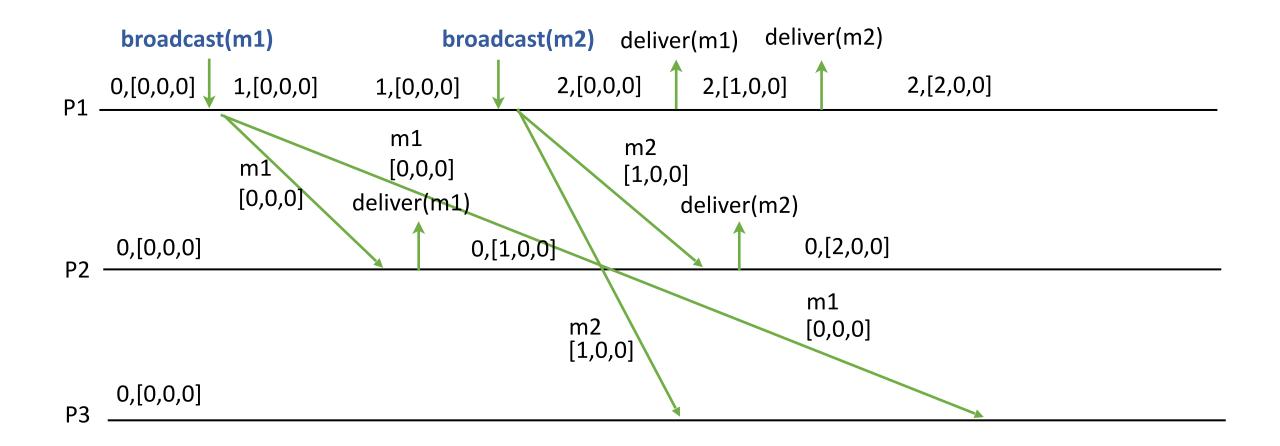


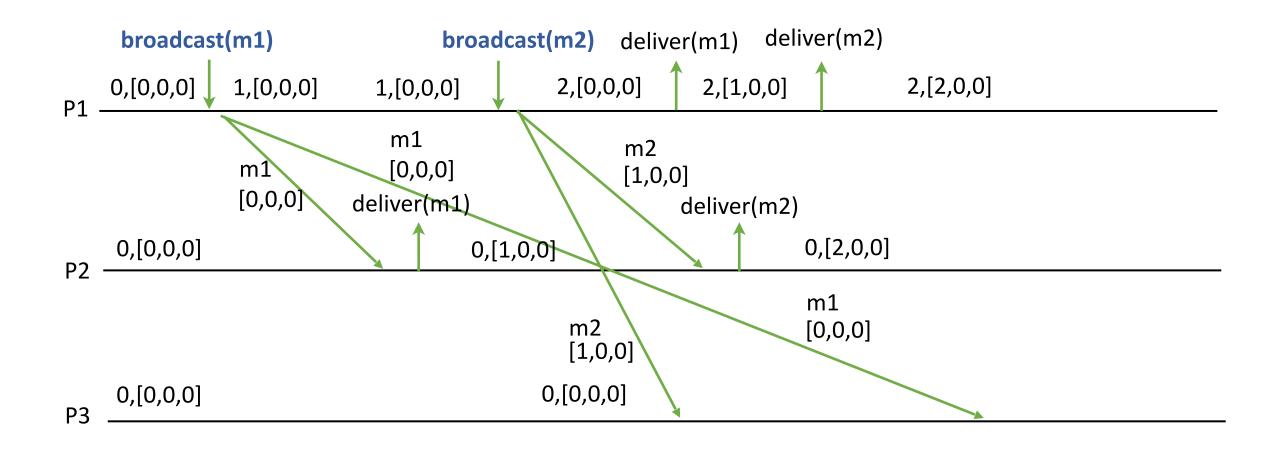


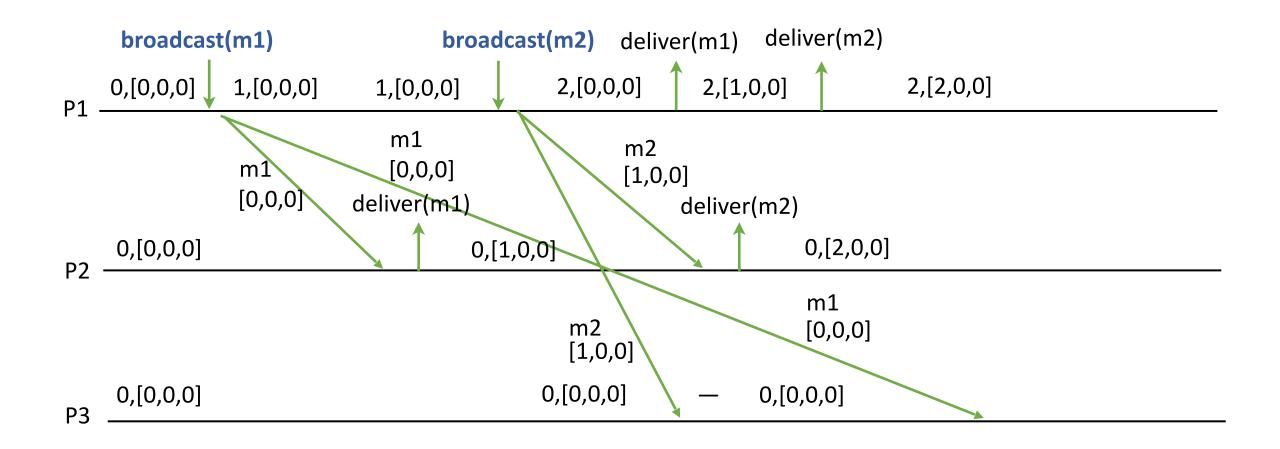


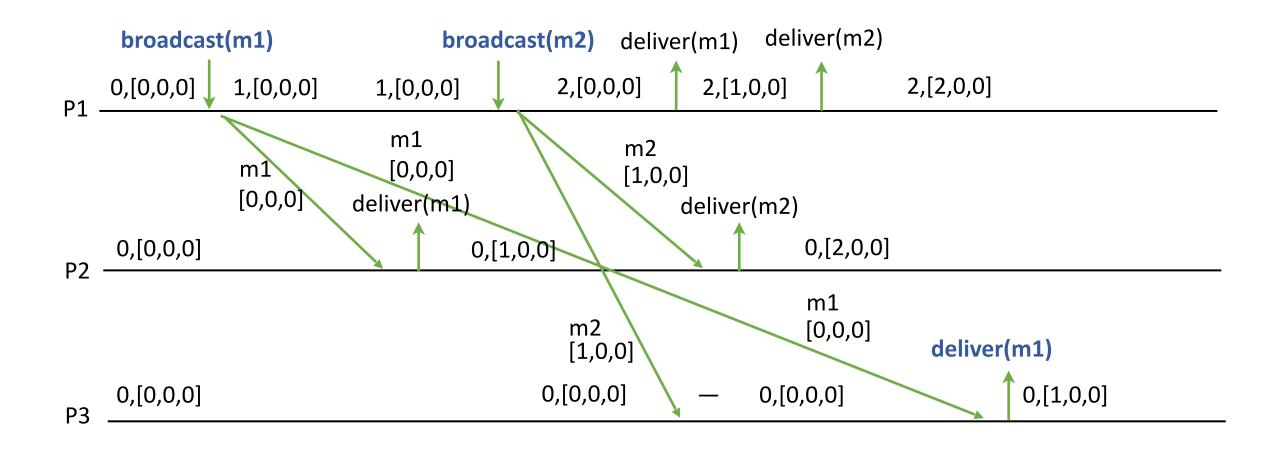


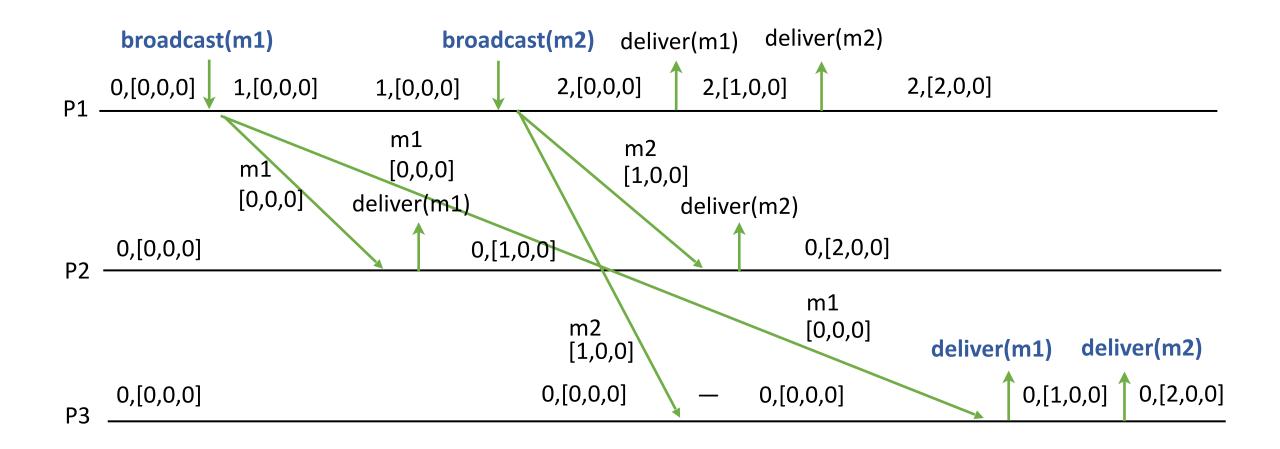












Modular Design

Application broadcast deliver	
crash Causal Broadcast broadcast deliver	
I Failure Detector	Reliable Broadcast
Channels	Channels

Implements: UniformCausalBroadcast (ucb). **Uses**: UniformReliableBroadcast (urb).

Implements: UniformCausalBroadcast (ucb).

Uses: UniformReliableBroadcast (urb).

Similarly Reliable broadcast can be used to get Reliable causal broadcast.

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upon event < Init > do

delivered := past := \emptyset

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Uses: UniformReliableBroadcast (urb).

upon event < Init > do

delivered := past := \emptyset

upon event < broadcast (m) > do
 trigger < urb, broadcast ([past, m]) >
 past := past U {[self, m]}

Similarly Reliable broadcast can be used to get Reliable causal broadcast.

Implements: UniformCausalBroadcast (ucb).

Uses: UniformReliableBroadcast (urb).

upon event < Init > do

delivered := past := \emptyset

Similarly Reliable broadcast can be used to get Reliable causal broadcast.

upon event < broadcast (m) > do
 trigger < urb, broadcast ([past, m]) >
 past := past U {[self, m]}

Every new message is added to past. This preserves the FIFO order property.

upon event <urb, deliver (pi, [pastm, m])> do
if m ∉ delivered then
forall [sn, n] ∈ pastm do
if n ∉ delivered then
trigger < deliver (sn, n) >
delivered := delivered U {n}
past := past U {[sn, n]}

upon event <urb, deliver (pi, [pastm, m])> do
if m \notin delivered then
forall [sn, n] \in pastm do
if n \notin delivered then
trigger < deliver (sn, n) >
delivered := delivered U {n}
past := past U {[sn, n]}

The set pastm is added to past. This preserves the transitivity property.

```
upon event <urb, deliver (pi, [pastm, m])> do
   if m ∉ delivered then
       forall [sn, n] ∈ pastm do
          if n ∉ delivered then
              trigger < deliver (sn, n) >
              delivered := delivered U \{n\}
              past := past U {[sn, n]}
      trigger < deliver (pi, m) >
      delivered := delivered U {m}
      past := past U {[pi, m]}
```

The set pastm is added to past. This preserves the transitivity property.

```
upon event <urb, deliver (pi, [pastm, m])> do
   if m ∉ delivered then
       forall [sn, n] ∈ pastm do
          if n ∉ delivered then
              trigger < deliver (sn, n) >
              delivered := delivered U \{n\}
              past := past U {[sn, n]}
      trigger < deliver (pi, m) >
      delivered := delivered U {m}
      past := past U {[pi, m]}
```

The set pastm is added to past. This preserves the transitivity property.

Every delivered message is added to past. This preserves the InOut property.

Observation

If we keep remembering the past, we eventually run out of space!



- Broadcast an ack when a message is delivered.
- Forget a message after receiving acks from all correct processes.

```
Implements: CausalOrderBroadcast (co).
Uses:
   ReliableBroadcast (rb).
   PerfectFailureDetector (P).
upon event < Init > do
   ...
   correct := \Pi
   ack(m) := \emptyset (for all m)
```

Protocol 1 + Garbage Collection

upon event < P, crash (pi) > do
 correct := correct \ {pi}

Protocol 1 + Garbage Collection

```
upon event < P, crash (pi) > do
  correct := correct \ {pi}
```

...

upon event <urb, deliver (p, Msg[pastm, m])> do

trigger <urb, broadcast (Ack[p, m])>

Protocol 1 + Garbage Collection

upon event < P, crash (pi) > do
 correct := correct \ {pi}

...

upon event <urb, deliver (p, Msg[pastm, m])> do

trigger <urb, broadcast (Ack[p, m])>

upon event <urb, deliver (p, Ack[s, m])> do
 ack(m) := ack(m) U {p}
 if correct ⊆ ack(m) then
 past := past \ {[s, m]}

Implements: UniformCausalBroadcast (ucb). **Uses**: UniformReliableBroadcast (urb).

```
upon event < Init > do
sq := 0
foreach pi in Π: VC[pi] := 0
```

```
upon event < broadcast (m) > do
VC' = VC[self ↦ sq]
trigger < urb, broadcast ([VC', m]) >
sq = sq + 1
```

```
upon event < broadcast (m) > do
VC' = VC[self ↦ sq]
trigger < urb, broadcast ([VC', m]) >
sq = sq + 1
```

```
upon event < urb, deliver (pj, [VCm, m]) > do
wait until (VC ≥ VCm)
trigger < deliver (pj, m) >
VC[pj] := VC[pj] + 1
```