# CSE113: Parallel Programming



#### • **Topics**:

- Intro to mutual exclusion
	- Different types of parallelism
	- Data conflicts
	- Protecting shared data

#### Announcements

- Second lecture in Module 2: mutexes!
- HW 2 will be assigned today at midnight. You'll have what you need to complete part 1 by end of today.
- No guarantee of homework help after 5 PM or weekends.

#### Announcements

- Midterm is in 2 weeks
	- In-person test
	- 3 pages of notes front and back (but no memorization questions)
	- 10% of your grade

# Previous quiz

# Previous quiz

It is possible to interleave the load and store operations of RMW atomic operations; however, it is so rare that it does not matter in practice.

# Mutex alternatives?

Other ways to implement accounts?

Atomic Read-modify-write (RMWs): primitive instructions that implement a read event, modify event, and write event indivisibly, i.e. it cannot be interleaved.

```
atomic_fetch_add(atomic_int * addr, int value) {
  int tmp = *addr; // read
  tmp += value; // modify
  *addr = tmp; // write
}
```
other operations: max, min, etc.

#### Modify these programs to use atomic RMWs

*Tyler's coffee addiction:*

atomic\_fetch\_add(&tylers\_account, -1);

*Tyler's employer*

atomic\_fetch\_add(&tylers\_account, 1);

time

time

#### Modify these programs to use atomic RMWs

*Tyler's coffee addiction:*

atomic\_fetch\_add(&tylers\_account, -1);

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atomic fetch add(&tylers account,  $-1$ );

time

atomic\_fetch\_add(&tylers\_account, 1);

time

### Previous quiz

A data conflict is when two threads access the same memory location.

# Embarrassingly parallel



# Embarrassingly parallel

**Note: Reductions have some parallelism in them, as seen in your homework.**



*Conflict because multiple threads write to the same location!*

# Previous quiz

How many interleavings are possible with 3 threads, each them executing 1 event?



# Previous quiz

How many extra arguments are required to turn a function into an SPMD function?



# SPMD programming model

**void increment\_array**(**int** \*a, **int** a\_size, **int** tid, **int** num\_threads) { for (int  $i = \frac{tid}{i}$ ;  $i < a$  size; i+=num threads) {  $a[i]++;$ }

iterations computed by thread 1



}

#### *switch to thread 1*

Assume 2 threads lets step through thread 1 i.e. tid  $= 1$ num threads  $= 2$ 

# Previous quiz

Write a few sentences about how you can remove data-conflicts from your program. We have mentioned a few ways in class, but feel free to mention other ways you can think of!

# Review

# Mutex Performance

Try to keep mutual exclusion sections small! Protect only data conflicts!

Code example with overhead



*Long periods of waiting in the threads*

# Mutex Performance

Try to keep mutual exclusion sections small! Protect only data conflicts!

Code example with overhead



*overlap the overhead (i.e. computation without any data conflicts)*

Lets say I have two accounts:

- Business account
- Personal account
- Need to protect both of them using a mutex
	- Easy, we can just the same mutex

Lets say I have two accounts:

- Business account
- Personal account
- No reason individual accounts can't be accessed in parallel

Lets say I have two accounts:

- Business account
- Personal account
- No reason individual accounts can't be accessed in parallel



*Long periods of waiting in the threads*

Mutexes are objects. We can create multiple versions of them to protect different shared data.

MutexP for personal account MutexB for business account



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MutexP for personal account MutexB for business account



# Managing multiple mutexes

Consider this increasingly elaborate scheme

My accounts start being audited by two agents:

- UCSC
- IRS
- They need to examine the accounts at the same time. They need to acquire both locks

# Managing multiple mutexes

}

```
void irs_audit() {
  for (int i = \emptyset; i < NUM_AUDITS; i++) {
     tylers_personal_account_mutex.lock();
     tylers_business_account_mutex.lock();
```
AUDIT(tylers\_personal\_account, tylers\_business\_account);

```
 tylers_personal_account_mutex.unlock();
   tylers_business_account_mutex.unlock();
 }
```

```
void ucsc_audit() {
  for (int i = 0; i < NUM_AUDITS; i++) {
     tylers_business_account_mutex.lock();
     tylers_personal_account_mutex.lock();
    AUDIT(tylers_personal_account, tylers_business_account);
     tylers_personal_account_mutex.unlock();
     tylers_business_account_mutex.unlock();
 }
}
```
• Our program deadlocked! What happened?



UCSC











• Our program deadlocked! What happened?

IRS has the personal mutex and won't release it until it acquires the business mutex. UCSC has the business mutex and won't release it until it acquires the personal mutex.

*This is called a deadlock! The locks must be acquired in the same order across the application.*


#### New material

Three properties

• **Mutual exclusion** - Only 1 thread can hold the mutex at a time. Critical sections cannot interleave

> *Other threads are allowed to request, but not acquire until the thread that has acquired the mutex releases it.*

concurrent execution

mutex request  $\parallel$  mutex acquire  $\parallel$  mutex request

mutex acquire

**disallowed!**

Three properties

• **Mutual exclusion** - Only 1 thread can hold the mutex at a time. Critical sections cannot interleave

> *Other threads are allowed to request, but not acquire until the thread that has acquired the mutex releases it.*

concurrent execution



Three properties

• **Deadlock Freedom -** If a thread has requested the mutex, and no thread currently holds the mutex, the mutex must be acquired by one of the requesting threads

concurrent execution

mutex request | mutex request

time

Three properties

• **Deadlock Freedom -** If a thread has requested the mutex, and no thread currently holds the mutex, the mutex must be acquired by one of the requesting threads

> Program cannot hang here Either thread 0 or thread 1 must acquire the mutex

concurrent execution

mutex request | mutex request

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> Program cannot hang here Either thread 0 or thread 1 must acquire the mutex

concurrent execution

mutex request | mutex request mutex acquire

**allowed**

Three properties

• **Deadlock Freedom -** If a thread has requested the mutex, and no thread currently holds the mutex, the mutex must be acquired by one of the requesting threads

> Program cannot hang here Either thread 0 or thread 1 must acquire the mutex

concurrent execution

mutex request | mutex request mutex acquire

**also allowed**

Three properties

• **Starvation Freedom** (*Optional*) - A thread that requests the mutex must eventually obtain the mutex.

*Thread 1 (yellow) requests the mutex but never gets it*

concurrent execution



Three properties

• **Starvation Freedom** (*Optional*) - A thread that requests the mutex must eventually obtain the mutex.

*Thread 1 (yellow) requests the mutex but never gets it*

concurrent execution



Difficult to provide in practice and timing variations usually provide this property naturally

Recap: three properties

- **Mutual Exclusion**: Two threads cannot be in the critical section at the same time
- **Deadlock Freedom**: If a thread has requested the mutex, and no thread currently holds the mutex, the mutex must be acquired by one of the requesting threads
- **Starvation Freedom** (*optional*): A thread that requests the mutex must eventually obtain the mutex.

# Building blocks

- Memory reads and memory writes
	- later: read-modify-writes
- We need to guarantee that our reads and writes actually go to memory.
	- And other properties we will see soon
- To do this, we will use C++ atomic operations

# A historical perspective

- Adding concurrency support to a programming language is hard!
- The memory model defines how threads can safely share memory
- Java tried to do this,

#### wikipedia

The original Java memory model, developed in 1995, was widely perceived as broken, preventing many runtime optimizations and not providing strong enough guarantees for code safety. It was updated through the Java Community Process, as Java Specification Request 133 (JSR-133), which took effect in 2004, for Tiger (Java 5.0).<sup>[1][2]</sup>

Brian Goetz (2019)

It is worth noting that **broken** techniques like double-checked locking are still **broken** under the new memory model, a

# A historical perspective

- How is C++?
- Has issues (imprecise, not modular)
	- but at least considered safe
	- Specification makes it difficult to reason about all programs
	- Open problem!
- Race-free program are safe! Use either locks or atomic variables.

# Our primitive instructions

- Types: atomic\_int
- Interface (C++ provides overloaded operators):
	- load
	- store
- Properties:
	- loads and stores will always go to memory.
	- compiler memory fence
	- hardware memory fence

- loads and stores will always go to memory
- Compiler example, performance difference

- loads and stores will always go to memory
- Compiler example, performance difference

```
int foo(int x) {
  x = 0;for (int i = 0; i < 2048; i++) {
     x++;
 }
   return x;
}
```

```
int foo(atomic x) {
   x.store(0);
  for (int i = 0; i < 2048; i++) {
    int tmp = x.load();
     tmp++;
     x.store(tmp);
 }
   return x.load();
}
```
- loads and stores will always go to memory
- Compiler example, performance difference
- Compiler makes reasoning about parallel code hard, but big performance improvements for sequential code:
	- $\bullet$  O(ITERS) vs. O(1)

- Compiler Fence
- Compiler can be aggressive with memory operations:
	- For non-atomic memory locations, the following optimizations are valid

- Compiler Fence
- Compiler can be aggressive with memory operations:
	- For non-atomic memory locations, the following optimizations are valid

 $a[i] = 0;$  $a[i] = 1;$ 

can be optimized to:

 $a[i] = 1;$ 

- Compiler Fence
- Compiler can be aggressive with memory operations:
	- For non-atomic memory locations, the following optimizations are valid

 $a[i] = 0;$  $a[i] = 1;$  $x = a[i];$  $x2 = a[i];$ 

can be optimized to: can be optimized to:

 $a[i] = 1;$ 

$$
x = a[i];
$$
  

$$
x2 = x;
$$

- Compiler Fence
- Compiler can be aggressive with memory operations:
	- For non-atomic memory locations, the following optimizations are valid



- Compiler Fence
- Compiler can be aggressive with memory operations:
	- For non-atomic memory locations, the following optimizations are valid
- And many others... especially when you consider mixing with other optimizations
	- Very difficult to understand when/where memory accesses will actually occur in your code

• Compiler Fence

Compiler cannot keep personal\_account in a register past the mutex



• Compiler Fence

what can go wrong if the compiler doesn't write values to memory?





• Compiler Fence

what can go wrong if the compiler doesn't write values to memory?

*initially personal\_account is 0*



• Compiler Fence

what can go wrong if the compiler doesn't write values to memory?



• Compiler Fence

what can go wrong if the compiler doesn't write values to memory?



*loads 0 writes 1*

• Compiler Fence

what can go wrong if the compiler doesn't write values to memory?



• Also provides a memory barrier




































































C0



C0



different architectures have different memory barriers

Intel X86 naturally manages caches in order

ARM and PowerPC let cache values flow out-of-order GPUs let caches flow out-of-order

RISC-V has two models: more like x86: easier to program more like ARM: faster and more energy efficient

*For mutexes, atomics will naturally handle the memory fences for us!*

## Atomics

- What do those fences (compiler and memory) give us?
- Atomics were designed so that we can implement things like mutexes!



## Atomics

- What do those fences (compiler and memory) give us?
- Atomics were designed so that we can implement things like mutexes!



C1 memory operations have **not** yet been performed and cache is invalidated

- We will just consider two threads for now, with thread ids 0, 1
- A first attempt:
	- A mutex contains a boolean.
	- The mutex value set to 0 means that it is free. 1 means that some thread is holding it.
	- To acquire the mutex, you wait until it is set to 0, then you store 1 in it.
	- To release the mutex, you set the mutex back to 0.

```
#include <atomic>
using namespace std;
class Mutex {
public:
  Mutex() {
    flag = 0;\mathbf{r}void lock();
  void unlock();
private:
  atomic_bool flag;
\} ;
```
mutex is initialized to "free"

atomic\_bool for our memory location

```
void lock() {
  while (flag.load() == 1);
  flag.setore(1);\overline{\mathbf{r}}
```
Once the mutex is available, we will claim it While the mutex is not available (i.e. another thread has it)

```
void lock() {
  while (flag.load() == 1);
  flag.store(1);\mathbf{\}
```
Once the mutex is available, we will claim it While the mutex is not available (i.e. another thread has it)

*What's up with this while loop?*



To release the mutex, we just set it back to 0 (available)

void **lock()** { **while**  $(flag.load() == 1)$ ;  $flag.store(1);$  $\}$ 

void unlock() {  $flag.store(0);$  $\mathcal{F}$ 

Thread 0: m.lock(); m.unlock();

Thread 1: m.lock(); m.unlock();

core 0

core 1

void **lock()** { **while**  $(flag.load() == 1)$ ;  $flag.store(1);$  $\}$ 

#### void unlock() {  $flag.setore(0);$  $\mathcal{F}$

Thread 0: m.lock(); m.unlock();

m.request

Thread 1: m.lock(); m.unlock();

core 0

core 1

void **lock()** { **while**  $(flag.load() == 1)$ ;  $flag.store(1);$  $\}$ 

#### void unlock() {  $flag.setore(0);$  $\mathcal{F}$





void **lock()** { **while**  $(flag.load() == 1)$ ;  $flag.store(1);$  $\}$ 

#### void unlock() {  $flag.setore(0);$  $\mathbf{B}$

Thread 0: m.lock(); m.unlock();



void **lock()** { **while**  $(flag.load() == 1)$ ;  $flag.store(1);$ }

#### void unlock() {  $flag.setore(0);$  $\mathbf{B}$

Thread 0: m.lock(); m.unlock();

Thread 1: m.lock(); m.unlock();



core 1

void **lock()** { **while**  $(flag.load() == 1)$ ;  $flag.store(1);$ }

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#### void unlock() {  $flag.setore(0);$ }

Thread 0: m.lock(); m.unlock();



void **lock()** { while  $(flag.load() == 1)$ ;  $flag.setore(1);$ }

void unlock() {  $flag.setore(0);$ }



Thread 1: m.lock(); m.unlock();

*Mutual Exclusion property! critical sections do not overlap!*



## Recall our previous analysis. What was core 1 probably doing?



## Recall our previous analysis. What was core 1 probably doing?





#### void unlock() {  $flag.setore(0);$  $\mathbf{r}$



Thread 1: m.lock(); m.unlock();

*Lets try another interleaving*





#### void unlock() {  $flag.setore(0);$  $\mathcal{F}$



Thread 1: m.lock(); m.unlock();

*Enter at almost the same time*



#### void **lock()** { while  $(flag.load() == 1)$ ;  $flag.store(1);$ }

#### void unlock() {  $flag.setore(0);$ }



Thread 1: m.lock(); m.unlock();

*Critical sections overlap! This mutex implementation is not correct!*



- Second attempt:
	- A flag for each thread (2 flags)
	- If you want the mutex, set your flag to 1.
	- Spin while the other flag is 1 (the other thread has the mutex)
	- To release the mutex, set your flag to 0

## #include <atomic> using namespace std;

```
class Mutex {
public:
  Mutex() {
    flag[0] = flag[1] = 0;\mathcal{F}
```

```
void lock();
void unlock();
```
#### private: atomic\_bool flag[2];  $\}$  ;

#### both initialized to 0

two flags this time

### void  $lock() \{$  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0 ? 1 : 0;$ while  $(flag[j].load() == 1)$ ; }

Thread id (0, or 1) Mark your intention to take the lock

Wait for other thread to leave the critical section



Thread id (0, or 1)

Mark your flag to say you have left the critical section.
void **lock()** {  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0$  ? 1 : 0; while  $(flag[j].load() == 1);$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\}$ 



Thread 1: m.lock(); m.unlock();

core 0

core 1

void **lock()** {  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0$  ? 1 : 0; while  $(flag[j].load() == 1);$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\}$ 





void **lock()** {  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0$  ? 1 : 0; while  $(flag[j].load() == 1);$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\}$ 





void **lock()** {  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0$  ? 1 : 0; while  $(flag[j].load() == 1);$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\}$ 







void unlock() {  $int i = thread_id;$  $flag[i].store(0);$ 



Thread 1: m.lock(); m.unlock();

*critical sections do not overlap!* 



void **lock()** {  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0$  ? 1 : 0; while  $(flag[j].load() == 1);$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\}$ 



#### Thread 1: m.lock(); m.unlock();

*Enter at almost the same time*



void **lock()** {  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0$  ? 1 : 0; while  $(flag[j].load() == 1);$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\}$ 









void **lock()** {  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0$  ? 1 : 0; while  $(flag[j].load() == 1);$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\}$ 





void  $lock() \{$  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0$  ? 1 : 0; while  $(flag[j].load() == 1)$ ;

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\}$ 



#### Thread 1: m.lock(); m.unlock();

*Both will spin forever!*

core 0 core 1 Mutex request Mutex request flag[0].store(1) flag[1].store(1) flag[1].load flag[0].load returns 1 returns 1  $\frac{f}{\lvert \text{flag}[0]}\rvert$ load  $\lvert \text{-}\rvert$  flag $\lvert 0\rvert$ .load  $\lvert \text{-}\rvert$  flag $\lvert 0\rvert$ .load flag[1].load  $\Box$  flag[1].load  $\Box$  flag[1].load  $\Box$  flag[1].load  $\Box$  flag[1].load  $\Box$  flag[1].load  $\Box$  flag[1].load

# Properties of mutexes

Three properties

• **Deadlock Freedom -** If a thread has requested the mutex, and no thread currently holds the mutex, the mutex must be acquired by one of the requesting threads

> Program cannot hang here Either thread 0 or thread 1 must acquire the mutex

concurrent execution

mutex request | mutex request

Third attempt:

```
class Mutex {
public:
  Mutex() {
    victim = -1;
  \}void lock();
  void unlock();
private:
  atomic_int victim;
\} ;
```
initialized to -1

back to a single variable

void **lock()** { victim.store(thread\_id); while  $(victim.load() == thread_id);$  $\}$ 

Victims only job is to spin Volunteer to be the victim



**No unlock!**

void **lock()** { victim.store(thread\_id); while  $(victim.load() == thread_id);$  $\mathbf{R}$ 

### void unlock() {}



void **lock()** { victim.store(thread\_id); while (victim.load( $\overline{)}$  == thread\_id);  $\mathbf{R}$ 

### void unlock() {}

#### Thread 0: m.lock(); m.unlock();

#### Mutex request





Thread 0: m.lock(); m.unlock();

> spins forever if the second thread never tries to take the mutex!









#### *Enter at almost the same time*





Thread 0: m.lock(); m.unlock();





















Implementation with flags works when they do not request at the same time

Implementation with victim works when they request at the same time

Finally, we can can make a mutex that works:

Use flags to mark interest

Use victim to break ties

Called the **Peterson Lock**

```
class Mutex {
public:
  Mutex() \{victim = -1;
    flag[0] = flag[1] = 0;\}
```

```
void lock();
void unlock();
```
### private:

```
atomic_int victim;
  atomic_bool flag[2];
\} ;
```
Initially: No victim and no threads are interested in the critical section

flags and victim

```
void lock() \{int j = thread_id == 0 ? 1 : 0;flag[thread_id].store(1);victim.store(thread_id);
  while (victim.load() == thread_id
         & 48 flag[j] == 1);
```
j is the other thread Mark ourself as interested volunteer to be the victim in case of a tie

Spin only if: there the other thread wants the lock as well, and I am the victim

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\mathbf{\}}$ 

mark ourselves as uninterested

### Previous flag issue

void lock() {  $int i = thread_id;$  $flag[i].store(1);$ int  $j = i == 0$  ? 1 : 0; while  $(flag[j].load() == 1);$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\}$ 



How does Peterson solve this?

*Both will spin forever!*



 $void lock() {$ int  $j = thread_id == 0 ? 1 : 0;$  $flag[thread_id].store(1);$ victim.store(thread\_id);  $while$  (victim.load() == thread\_id  $& 8 & 1 = 1;$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$ }







 $void lock() {$ int  $j = thread_id == 0 ? 1 : 0;$  $flag[thread_id].store(1);$ victim.store(thread\_id);  $while$  (victim.load() == thread\_id  $& 8 & 1 = 1;$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$ }





 $void lock() {$ int  $j = thread_id == 0 ? 1 : 0;$ flag[thread\_id].store(1); victim.store(thread\_id);  $while$  (victim.load() == thread\_id  $& 8 & 1 = 1;$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$ }



 $1:$  $k()$ ;  $ock()$  ;





void  $lock() \{$ int  $j = thread_id == 0 ? 1 : 0;$ flag[thread\_id].store(1); victim.store(thread\_id);  $while$  (victim.load() == thread\_id  $& 8 & 1ag[j] == 1);$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$ }



Thread 1: m.lock(); m.unlock();

#### Mutex request



void  $lock() \{$ int  $j = thread_id == 0 ? 1 : 0;$ flag[thread\_id].store(1); victim.store(thread\_id);  $while$  (victim.load() == thread\_id  $& 8 & 1 = 1;$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$ }



core 0 core 1 Mutex request Mutex request flag[0].store(1) flag[1].store(1) victim.store(0) victim.store(1)  $flag[1].load$  victim.load 1 0 flag[0].load victim.load 1 0 Mutex acquire Critical section  $flag[1].load$  victim.load 1 0  $flag[1].load$  victim.load 1 0 Mutex release flag[1].store(0) flag[1].load victim.load 0 0 Mutex acquire

### Previous victim issue

void **lock()** { victim.store(thread\_id); while  $(victim.load() == thread_id);$  $\mathcal{E}$ 

### void unlock() {}

Thread 0: m.lock(); m.unlock();

*will spin forever!*

core 0 Mutex request victim.store(1)  $\leftarrow$  victim.load victim.load  $\Box$  victim.load  $\Box$  victim.load  $\Box$  victim.load  $\Box$  victim.load  $\Box$  victim.load  $\Box$  victim.load

## previous flag issue

void  $lock() \{$ int  $j = thread_id == 0 ? 1 : 0;$ flag[thread\_id].store(1); victim.store(thread\_id);  $while$  (victim.load() == thread\_id  $88$  flag[j] == 1);

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\mathcal{F}$ 

#### Thread 0: m.lock(); m.unlock();

#### Mutex request



## previous flag issue

void lock() { int  $j = thread_id == 0 ? 1 : 0;$ flag[thread\_id].store(1); victim.store(thread\_id); while  $(victim.load() == thread_id)$  $& 8 & 1 = 1;$ 

void unlock() {  $int i = thread_id;$  $flag[i].store(0);$  $\mathcal{F}$ 

Thread 0: m.lock(); m.unlock();



we can enter critical section because the other thread isn't interested

# This lock satisfies the two critical properties

- Mutual exclusion
- Deadlock freedom
- *More formal proof given in the textbook*
recall the starvation property:

*Thread 1 (yellow) requests the mutex but never gets it*

concurrent execution





at this point, C1 is the victim and is spinning

concurrent execution





at this point, C1 is the victim and is spinning





at this point, C1 is the victim and is spinning



Threads take turns in Peterson algorithm. It is starvation free.



at this point, C1 is the victim and is spinning



#### Mutex Implementations

Peterson only works with 2 threads.

Generalizes to the Filter Lock (Read chapter 2 in the book, part 1 of your homework!)

## Check implementations

- Thread sanitizer provided in Clang
- Checks for "data races"
	- Generally can help you check if you've used mutexes correctly (protecting all shared memory accesses).
	- Also: If you don't implement your mutexes correctly, you will probably have data races
	- This should hold for your next assignments too
	- Can also check for deadlock based on lock inversion
- Checking tool: if you pass, it doesn't mean your code is correct

## Check implementations

• Why not run all the time with thread sanitizer? Overhead!

#### Back to Mutex Implementations

Peterson only works with 2 threads.

Generalizes to the Filter Lock (Read chapter 2 in the book, part 1 of your homework!)

#### Historical perspective

- These locks are not very performant compared to modern solutions
	- Your HW will show this
- However, they are academically interesting: they can be implemented with plain loads and stores
- We will now turn our attention to more performant implementations that use RMWs

# Start by revisiting our first mutex implementation

- A first attempt:
	- A mutex contains a boolean.
	- The mutex value set to 0 means that it is free. 1 means that some thread is holding it.
	- To lock the mutex, you wait until it is set to 0, then you store 1 in the flag.
	- To unlock the mutex, you set the mutex back to 0.
- Let's remember why it was buggy

**Buggy Mutex implementation: Analysis**

void **lock()** { **while**  $(flag.load() == 1)$ ;  $flag.setore(1);$ }

void unlock() {  $flag.setore(0);$ }



Thread 1: m.lock(); m.unlock();

*Critical sections overlap! This mutex implementation is not correct!*



# What went wrong?

- The load and stores from two threads interleaved
	- What if there was a way to prevent this?

# What went wrong?

- The load and stores from two threads interleaved
	- What if there was a way to prevent this?
- Atomic RMWs
	- operate on atomic types (we already have atomic types)
	- recall the non-locking bank accounts: atomic\_fetch\_add(**atomic** \*a, **value** v);

### What is a RMW

A read-modify-write consists of:

- *read*
- *modify*
- *write*

done atomically, i.e. they cannot interleave.

Typically returns the value (in some way) from the read.

#### atomic\_fetch\_add

Recall the lock free account

Atomic Read-modify-write (RMWs): primitive instructions that implement a read event, modify event, and write event indivisibly, i.e. it cannot be interleaved.

```
atomic_fetch_add(atomic_int * addr, int value) {
  int tmp = *addr; // readtmp += value; // modify
  *addr = tmp; // write
}
```
#### atomic\_fetch\_add

Recall the lock free account

Atomic Read-modify-write (RMWs): primitive instructions that implement a read event, modify event, and write event indivisibly, i.e. it cannot be interleaved.

```
int atomic_fetch_add(atomic_int * addr, int value) {
  int stash = *addr; // read
  int new value = value + stash; // modify
   *addr = new value; // write
  return stash; // return previous value in the memory location
}
```
*Tyler's coffee addiction:*

atomic\_fetch\_add(&tylers\_account, -1);

*Tyler's employer*

atomic\_fetch\_add(&tylers\_account, 1);

time

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atomic fetch add(&tylers account, 1);

*Tyler's coffee addiction:*

atomic\_fetch\_add(&tylers\_account, -1);

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atomic\_fetch\_add(&tylers\_account, 1);

```
tmp = tylers account.load();
tmp - = 1;tylers account.store(tmp);
```
time

```
tmp = tylers_account.load();
tmp += 1;tylers account.store(tmp);
```
*Tyler's coffee addiction:*

time

atomic\_fetch\_add(&tylers\_account, -1);

#### *Tyler's employer*

atomic\_fetch\_add(&tylers\_account, 1);

```
tmp = tylers account.load();
tmp - = 1;tylers account.store(tmp);
```
cannot interleave!

```
tmp = tylers_account.load();
tmp += 1;tylers account.store(tmp);
```
*Tyler's coffee addiction:*

atomic fetch\_add(&tylers\_account, -1);

#### *Tyler's employer*

```
atomic fetch add(&tylers account, 1);
```


#### RMW-based locks

• A few simple RMWs enable lots of interesting mutex implementations

- Simplest atomic RMW will allow us to implement an:
- N-threaded mutex with 1 bit!

**value** atomic\_exchange(**atomic** \*a, **value** v);

Loads the value at a and stores the value in  $\nu$  at a. Returns the value that was loaded.

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```
value atomic_exchange(atomic *a, value v) {
  value tmp = a.load();
   a.store(v);
   return tmp;
}
```


Lets make a mutex with just one atomic bool!



#### Lets make a mutex with just one atomic bool!

initialized to false

one atomic flag



#### Lets make a mutex with just one atomic bool!

initialized to false

**main idea:**

The flag is false when the mutex is free.

The flag is true when some thread has the mutex.

one atomic flag





So what's going on?

# void lock() {  $while$  (atomic\_exchange(&flag, true) == true);

**Two cases**:

So what's going on?

**mutex is free**: the value loaded is false. We store true. The value returned is false, so we don't spin

**mutex is taken**: the value loaded is true, we put the SAME value back (true). The returned value is true, so we spin.



Unlock is simple: just store false to the flag, marking the mutex as available.

#### Analysis

#### void **lock()** {  $while$  (atomic\_exchange(&flag, true) == true);

Thread 0: m.lock();

m.unlock(); m.unlock(); Thread 1: m.lock();

}

void unlock() { flag.store(false); }

core 0

core 1

#### Analysis

#### void **lock()** { while  $(atomic\_exchange(8flag, true) == true)$ ;

Thread 0: m.lock(); m.unlock();

Thread 1: m.lock(); m.unlock();

}

void unlock() { flag.store(false); }



#### Analysis

#### void **lock()** { while  $(atomic\_exchange(8flag, true) == true)$ ;

Thread 0: m.lock(); m.unlock();

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Thread 0: m.lock(); m.unlock();

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void unlock() { flag.store(false); }



core 1

#### void **lock()** { while  $(atomic\_exchange(8flag, true) == true)$ ; }

Thread 0: m.lock(); m.unlock();

Thread 1: m.lock(); m.unlock();

void unlock() { flag.store(false); }

mutex works with one thread

core 0 core 1 EXCH() returns false Mutex request Mutex acquire critical section flag.store(false) Mutex release

#### void **lock()** {  $while$  (atomic\_exchange(&flag, true) == true);

Thread 0: m.lock(); m.unlock();

Thread 1: m.lock(); m.unlock();

}

void unlock() { flag.store(false); }



#### void **lock()** { while  $(atomic\_exchange(8flag, true) == true)$ ;

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#### void **lock()** { while  $(atomic\_exchange(8flag, true) == true);$  $\mathbf{B}$

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#### void **lock()** { while  $(atomic\_exchange(8flag, true) == true);$ }

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#### **what about interleavings?**

